

# Lensing Basics: II. Basic Theory

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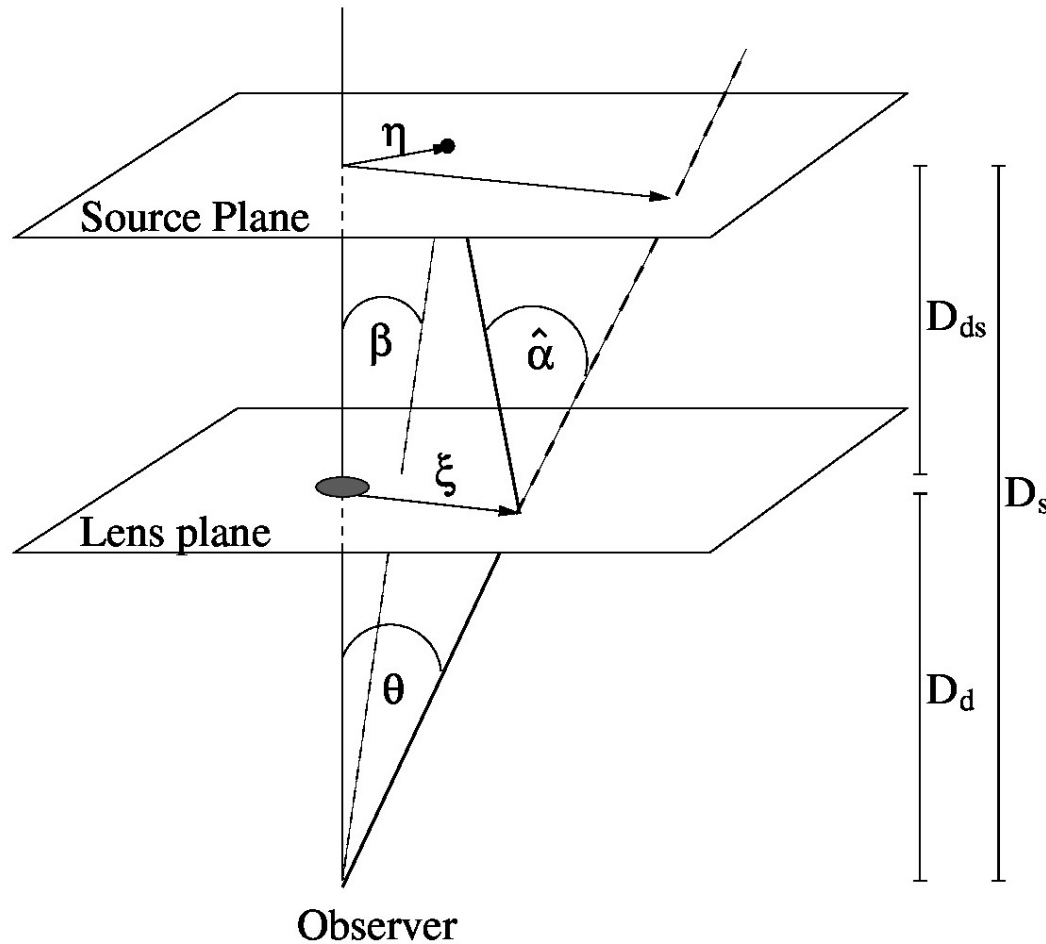
University of California Santa Barbara

KIPAC, Stanford University

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# Lens equation



$$\eta = \frac{D_s}{D_d} \xi - D_{ds} \hat{\alpha}(\xi)$$

In terms of angular coord.:

$$\eta = D_s \beta$$

$$\xi = D_d \theta$$

$$\beta = \theta - \alpha(\theta)$$

where

$$\alpha(\theta) = \frac{D_{ds}}{D_s} \hat{\alpha}(D_d \theta)$$

[Schneider et al. 2006]

# Deflection angle

Recall from General Relativity:

$$\hat{\alpha} = \frac{4GM}{c^2\xi}$$

For weak gravitational field and small deflection angles (*geometrically-thin lens*), a light ray with spatial trajectory  $(\xi_1(\lambda), \xi_2(\lambda), r_3(\lambda))$  that passes through distribution with 3D density  $\rho(\mathbf{r})$  will be deflected by

$$\hat{\alpha}(\boldsymbol{\xi}) = \frac{4G}{c^2} \int d^2\xi' \underbrace{\int dr'_3 \rho(\xi'_1, \xi'_2, r'_3)}_{\Sigma(\boldsymbol{\xi}')} \frac{\boldsymbol{\xi} - \boldsymbol{\xi}'}{|\boldsymbol{\xi} - \boldsymbol{\xi}'|^2}$$

# Scaled deflection angle

recall  $\alpha(\boldsymbol{\theta}) = \frac{D_{\text{ds}}}{D_{\text{s}}} \hat{\alpha}(D_{\text{d}}\boldsymbol{\theta})$

$$\alpha(\boldsymbol{\theta}) = \frac{1}{\pi} \int_{\mathfrak{R}^2} d^2\theta' \kappa(\boldsymbol{\theta}') \frac{\boldsymbol{\theta} - \boldsymbol{\theta}'}{|\boldsymbol{\theta} - \boldsymbol{\theta}'|^2}$$

where  $\kappa$  is the **dimensionless surface mass density** (a.k.a. **convergence**)

$$\kappa(\boldsymbol{\theta}) = \frac{\Sigma(D_{\text{d}}\boldsymbol{\theta})}{\Sigma_{\text{cr}}}$$

and  $\Sigma_{\text{cr}}$  is the **critical surface mass density**

$$\Sigma_{\text{cr}} = \frac{c^2}{4\pi G} \frac{D_{\text{s}}}{D_{\text{d}} D_{\text{ds}}}$$

# Lens potential

$$\alpha(\boldsymbol{\theta}) = \frac{1}{\pi} \int_{\mathfrak{R}^2} d^2\theta' \kappa(\boldsymbol{\theta}') \frac{\boldsymbol{\theta} - \boldsymbol{\theta}'}{|\boldsymbol{\theta} - \boldsymbol{\theta}'|^2}$$

Using  $\nabla \ln |\boldsymbol{\theta}| = \boldsymbol{\theta}/|\boldsymbol{\theta}|^2$

$$\alpha(\boldsymbol{\theta}) = \nabla \psi(\boldsymbol{\theta})$$

where the **lens potential** is

$$\psi(\boldsymbol{\theta}) = \frac{1}{\pi} \int_{\mathfrak{R}^2} d^2\theta' \kappa(\boldsymbol{\theta}') \ln |\boldsymbol{\theta} - \boldsymbol{\theta}'|$$

that satisfies the Poisson equation:

$$\nabla^2 \psi = 2\kappa$$

# Fermat potential

Define scalar function known as the **Fermat potential**

$$\tau(\boldsymbol{\theta}; \boldsymbol{\beta}) = \frac{1}{2}(\boldsymbol{\theta} - \boldsymbol{\beta})^2 - \psi(\boldsymbol{\theta})$$

It is a function of  $\boldsymbol{\theta}$  with  $\boldsymbol{\beta}$  as a parameter

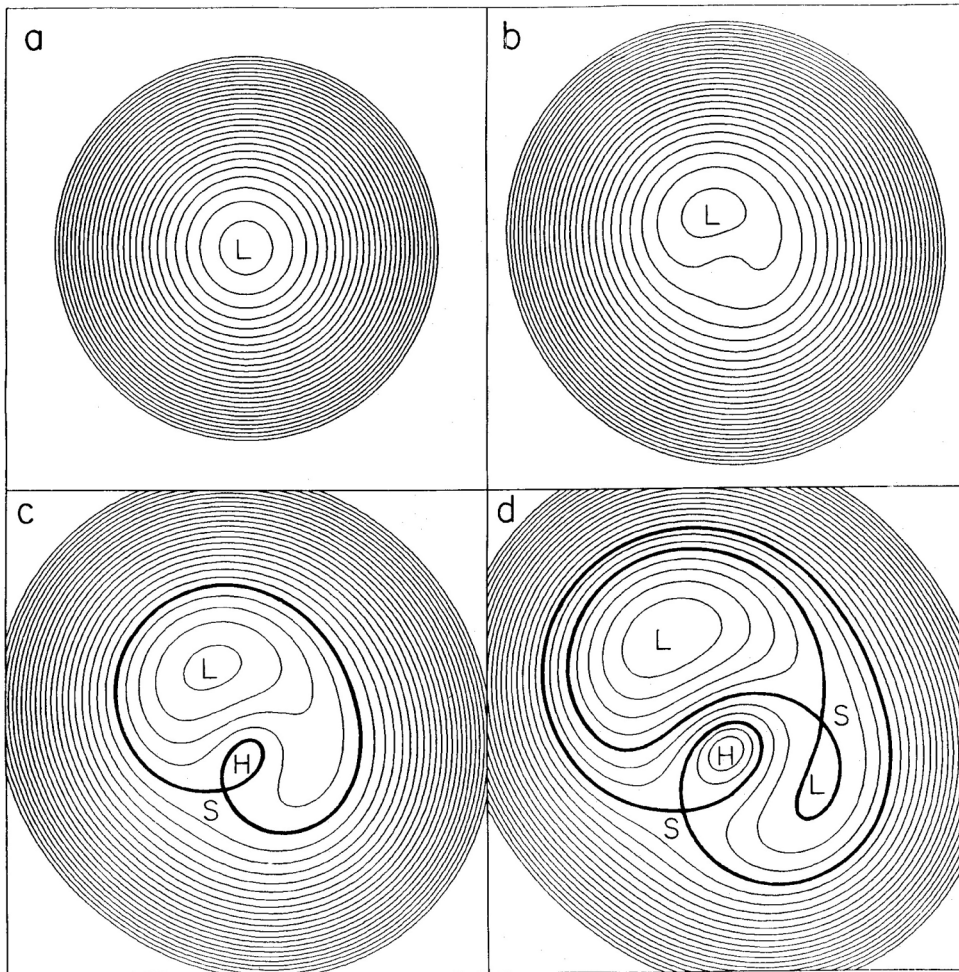
Note:

$$\nabla \tau(\boldsymbol{\theta}; \boldsymbol{\beta}) = 0$$

yields the lens equation  $\boldsymbol{\beta} = \boldsymbol{\theta} - \boldsymbol{\alpha}(\boldsymbol{\theta})$

# Fermat's Principle

Fermat potential  $\tau \propto$  excess time delay  $t$



Fermat's Principle:

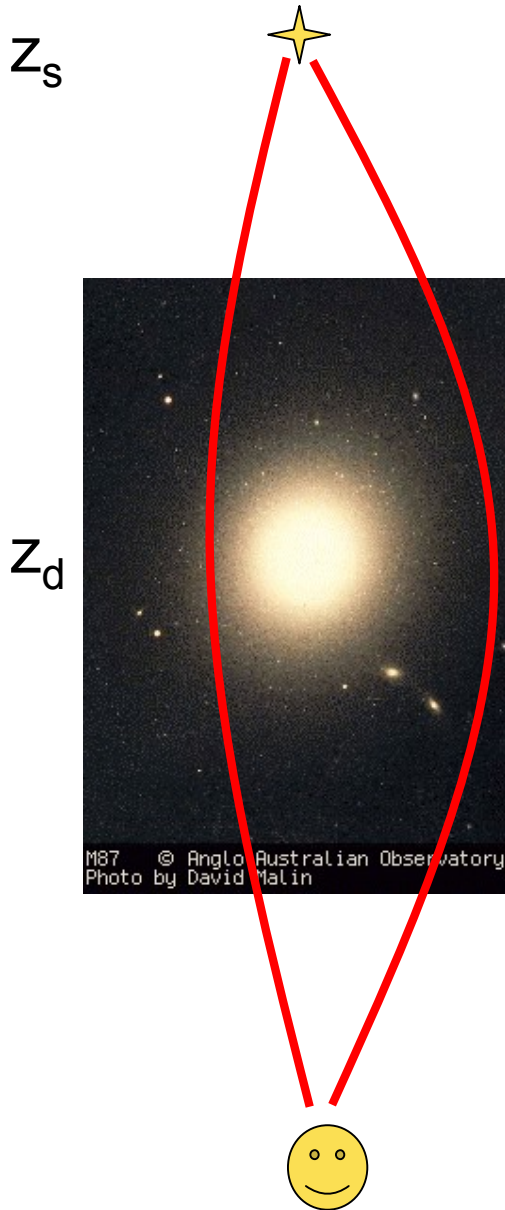
rays of light traverse the path of stationary optical length with respect to variations of the path

i.e.,

$$\nabla t = \nabla \tau = 0$$

[Blandford & Narayan 1986]

# Brief recap



Given a mass distribution  $\rho(\mathbf{r})$ , redshifts  $z_d, z_s$

➔  $\kappa(\theta)$  [convergence]

➔  $\alpha(\theta)$  [scaled deflection angle]

$$\alpha(\theta) = \frac{1}{\pi} \int_{\mathbb{R}^2} d^2\theta' \kappa(\theta') \frac{\theta - \theta'}{|\theta - \theta'|^2}$$

lens equation (governs light paths)

$$\beta = \theta - \alpha(\theta)$$

**Lenses are your dark matter goggles**

➔  $\psi(\theta)$  [lens potential]

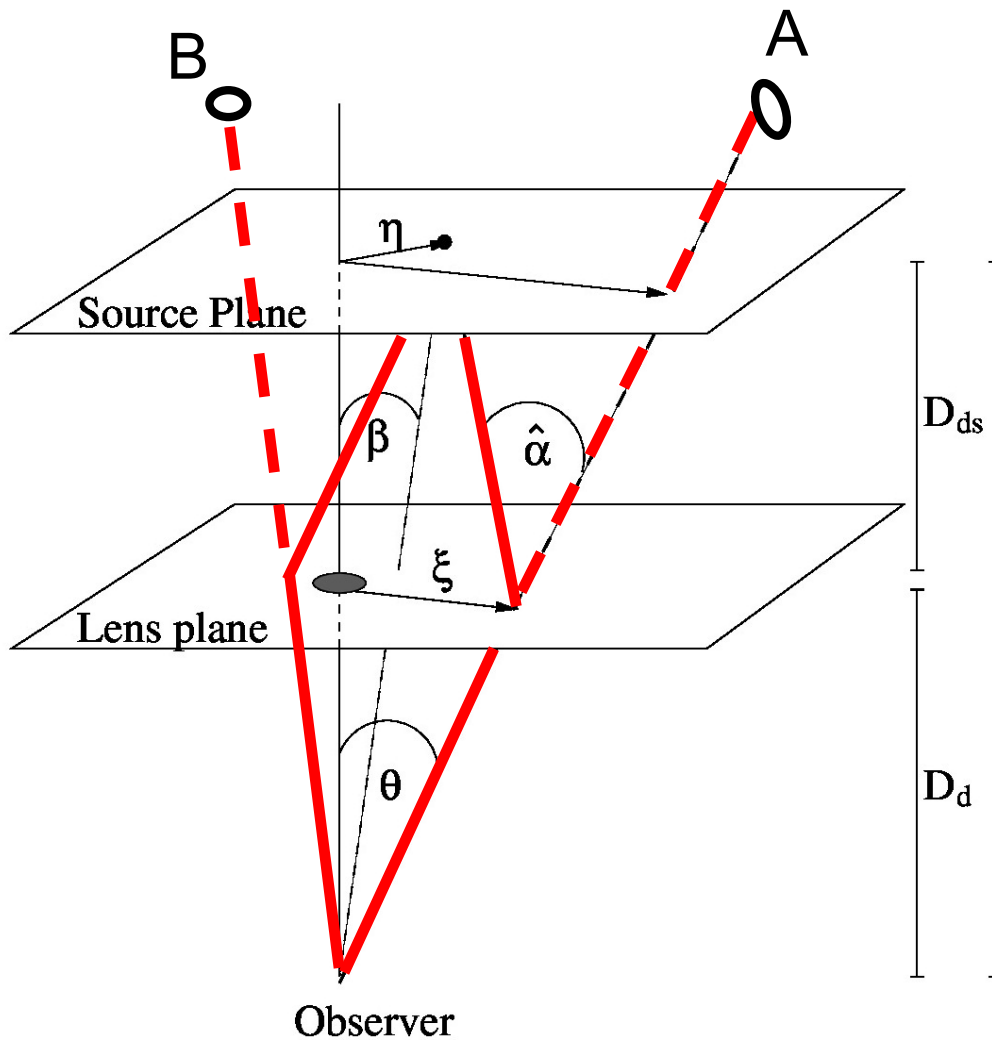
$$\nabla^2 \psi = 2\kappa$$

➔  $\tau(\theta; \beta)$  [Fermat potential]

$$\tau(\theta; \beta) = \frac{1}{2}(\theta - \beta)^2 - \psi(\theta) \quad 8$$



# Time delay



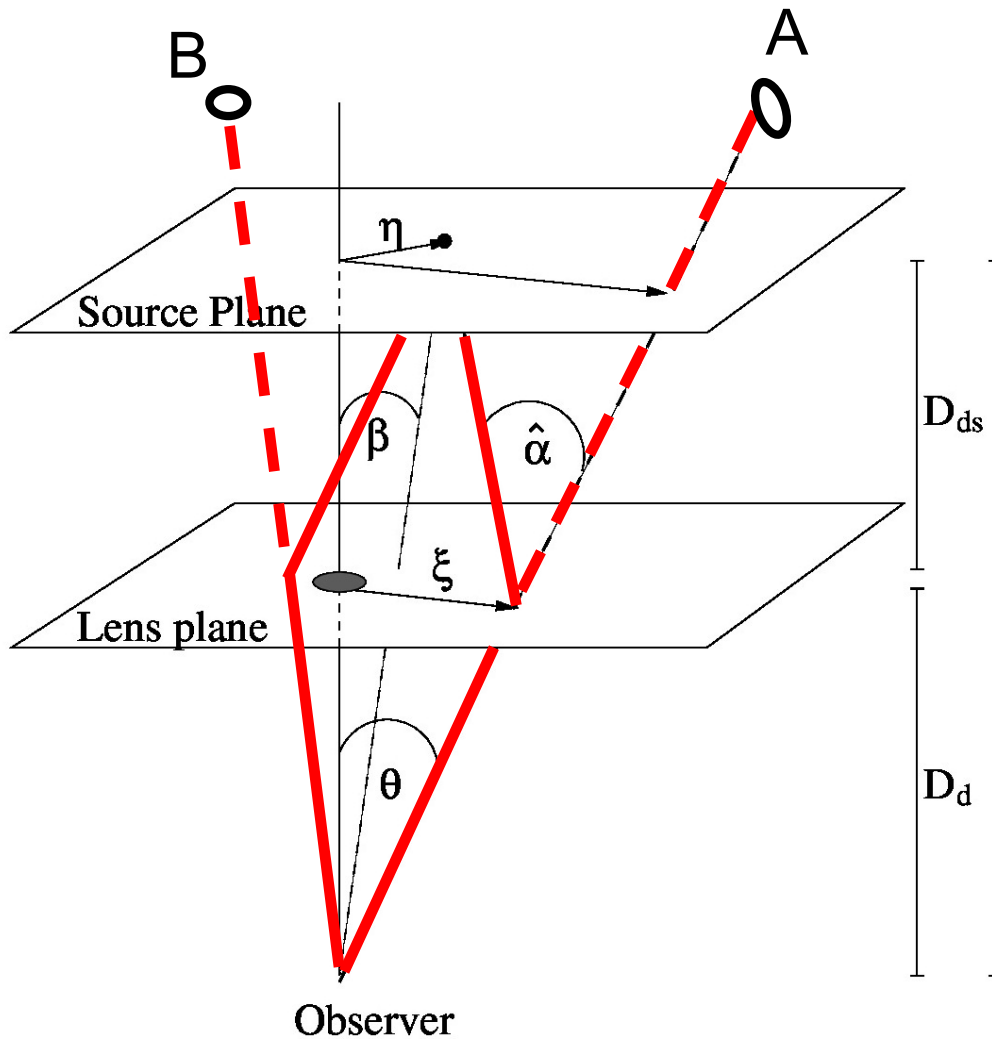
Recall Fermat potential

$$\tau(\boldsymbol{\theta}; \boldsymbol{\beta}) = \frac{1}{2}(\boldsymbol{\theta} - \boldsymbol{\beta})^2 - \psi(\boldsymbol{\theta})$$

Excess time delay relative to the case of no lensing is

$$t(\boldsymbol{\theta}; \boldsymbol{\beta}) = \frac{D_d D_s}{c D_{ds}} (1 + z_d) \tau(\boldsymbol{\theta}; \boldsymbol{\beta})$$

# Time delay



Recall Fermat potential

$$\tau(\boldsymbol{\theta}; \boldsymbol{\beta}) = \frac{1}{2}(\boldsymbol{\theta} - \boldsymbol{\beta})^2 - \psi(\boldsymbol{\theta})$$

Excess time delay relative to the case of no lensing is

$$t(\boldsymbol{\theta}; \boldsymbol{\beta}) = \frac{D_d D_s}{c D_{ds}} (1 + z_d) \tau(\boldsymbol{\theta}; \boldsymbol{\beta})$$

$\equiv D_{\Delta t} \propto H_0^{-1}$  depends on lens mass distrib.

depends on cosmology

→ **Cosmology Probe**

[Schneider et al. 2006]

# Magnification

Lensing conserves surface brightness

Flux  $F$  = surface brightness  $\times$  solid angle

Magnification =  $F_{\text{observed}} / F_{\text{intrinsic}} = d\Omega_{\text{observed}} / d\Omega_{\text{intrinsic}}$

Define Jacobian matrix:

$$\mathcal{A}(\boldsymbol{\theta}) = \frac{\partial \boldsymbol{\beta}}{\partial \boldsymbol{\theta}} \quad \text{with} \quad \mathcal{A}_{ij} = \frac{\partial \beta_i}{\partial \theta_j}$$

source plane  
lens plane

**Magnification factor** is

$$\mu(\boldsymbol{\theta}) = \frac{1}{\det \mathcal{A}(\boldsymbol{\theta})}$$

- $\mu > 0$  : positive parity
- $\mu < 0$  : negative parity (mirror image of source)
- $\det A = 0$  : critical points/curves

# Image distortion I

Rewrite Jacobian matrix:

$$\mathcal{A}(\boldsymbol{\theta}) = \frac{\partial \boldsymbol{\beta}}{\partial \boldsymbol{\theta}} = \left( \delta_{ij} - \frac{\partial^2 \psi(\boldsymbol{\theta})}{\partial \theta_i \partial \theta_j} \right) = \begin{pmatrix} 1 - \kappa - \gamma_1 & -\gamma_2 \\ -\gamma_2 & 1 - \kappa + \gamma_1 \end{pmatrix}$$

where  $\gamma_1$  and  $\gamma_2$  are the two components of **shear**

$$\gamma \equiv \gamma_1 + i\gamma_2 = |\gamma|e^{2i\varphi}$$

$$\gamma_1 = \frac{1}{2}(\psi_{,11} - \psi_{,22}) \quad \gamma_2 = \psi_{,12}$$

Magnification in terms of  $\kappa$  and  $\gamma$  is:

$$\mu = \frac{1}{\det \mathcal{A}} = \frac{1}{(1 - \kappa)^2 - |\gamma|^2}$$

# Image distortion II

Surface brightness conservation:

$$I(\boldsymbol{\theta}) = I^{(s)}[\boldsymbol{\beta}(\boldsymbol{\theta})]$$

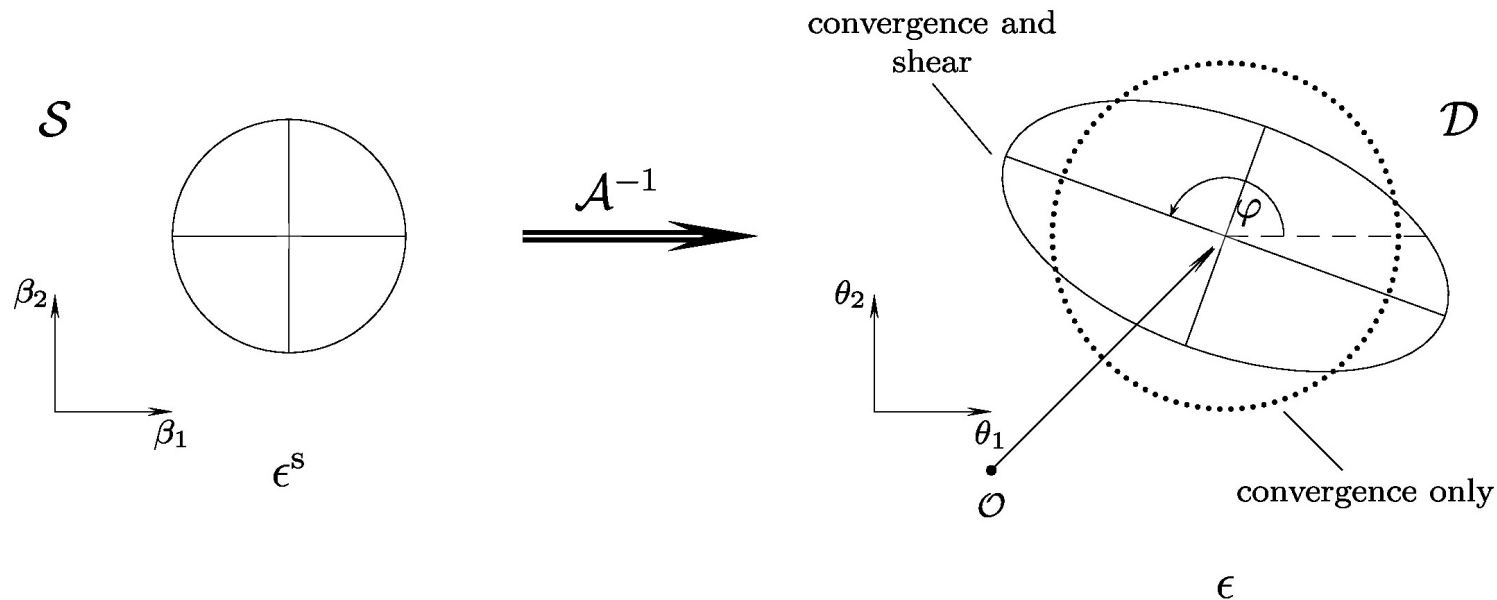
To visualize distortion, consider locally linearized lens eq.:

$$\boldsymbol{\beta} - \boldsymbol{\beta}_0 = \mathcal{A}(\boldsymbol{\theta}_0) \cdot (\boldsymbol{\theta} - \boldsymbol{\theta}_0)$$

Question: for an infinitesimally small circular source,  
what would the shape of its lensed image be?

- (1) Circular
- (2) Elliptical
- (3) Boxy
- (4) Irregular
- (5) None of the above

# Image distortion III



Credit: M. Bradac

The lensed image of a small circular source with radius  $R$  is an ellipse

Major axis:

$$\frac{R}{1 - \kappa - |\gamma|} = \frac{R}{(1 - \kappa)(1 - |g|)}$$

Minor axis:

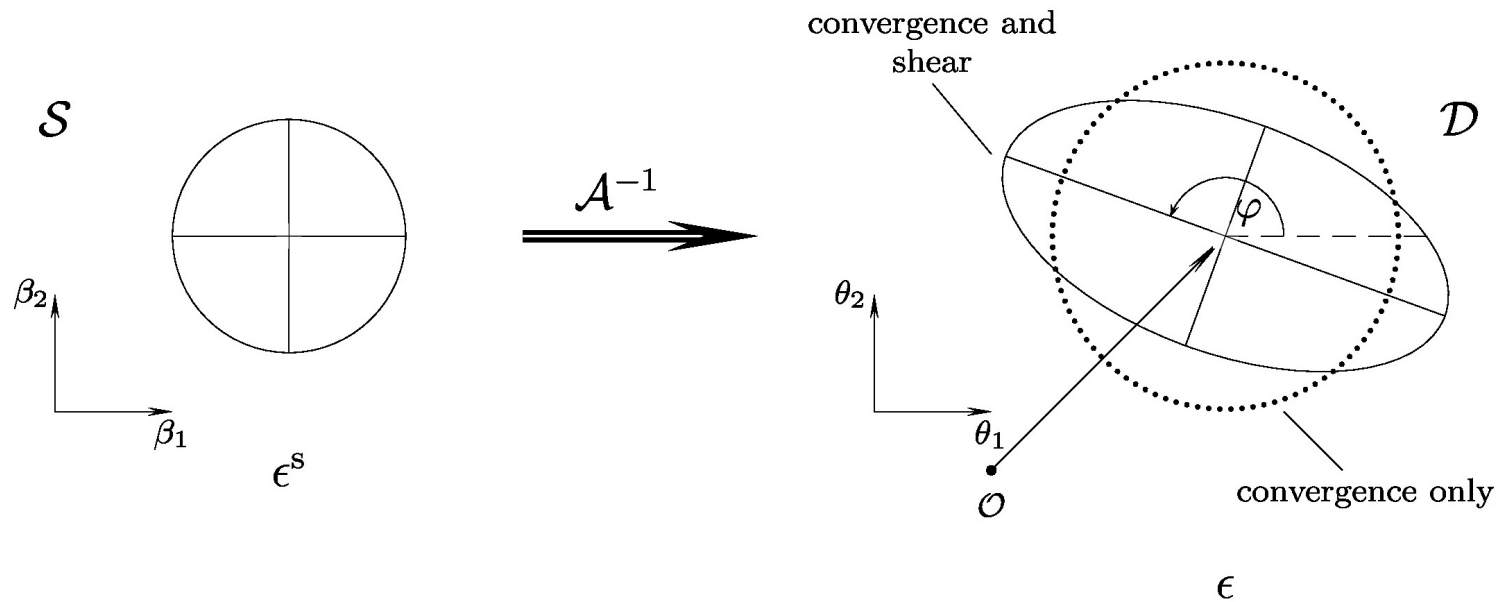
$$\frac{R}{1 - \kappa + |\gamma|} = \frac{R}{(1 - \kappa)(1 + |g|)}$$

reduced shear  $g(\theta) = \frac{\gamma(\theta)}{[1 - \kappa(\theta)]}$

Angle of major axis from  $\theta_1$  the same as the shear angle  $\varphi$

[Exercise: show these properties. Hint: try  $\beta(\lambda) = \beta_0 + R(\cos \lambda, \sin \lambda)$ ]

# Image distortion IV



Credit: M. Bradac

Axis ratio of ellipse:

$$\frac{b}{a} = \frac{R}{(1 - \kappa)(1 + |g|)} / \frac{R}{(1 - \kappa)(1 - |g|)} = \frac{1 - |g|}{1 + |g|}$$

➔ shapes of lensed images yield estimate of **reduced shear**

$$|g| = \frac{1 - b/a}{1 + b/a}$$

BUT sources are not intrinsically round...

➔ average over many sources, and assume intrinsic ellipticities are *randomly oriented*

# Shear and convergence

Recall

$$\gamma_1 = \frac{1}{2}(\psi_{,11} - \psi_{,22}) \quad \gamma_2 = \psi_{,12}$$

$$\psi(\boldsymbol{\theta}) = \frac{1}{\pi} \int_{\mathfrak{R}^2} d^2\theta' \kappa(\boldsymbol{\theta}') \ln |\boldsymbol{\theta} - \boldsymbol{\theta}'|$$

Shear can therefore be written as

$$\gamma(\boldsymbol{\theta}) = \frac{1}{\pi} \int_{\mathfrak{R}^2} d^2\theta' \mathcal{D}(\boldsymbol{\theta} - \boldsymbol{\theta}') \kappa(\boldsymbol{\theta}')$$

$$\mathcal{D}(\boldsymbol{\theta}) \equiv -\frac{\theta_1^2 - \theta_2^2 + 2i\theta_1\theta_2}{|\boldsymbol{\theta}|^4} = \frac{-1}{(\theta_1 - i\theta_2)^2}$$

Inverting this:

$$\kappa(\boldsymbol{\theta}) - \kappa_0 = \frac{1}{\pi} \int_{\mathfrak{R}^2} d^2\theta' \mathcal{R}e [\mathcal{D}^*(\boldsymbol{\theta} - \boldsymbol{\theta}') \gamma(\boldsymbol{\theta}')] ]$$

➔ mass reconstruction from weak lensing



# Classification of ordinary images

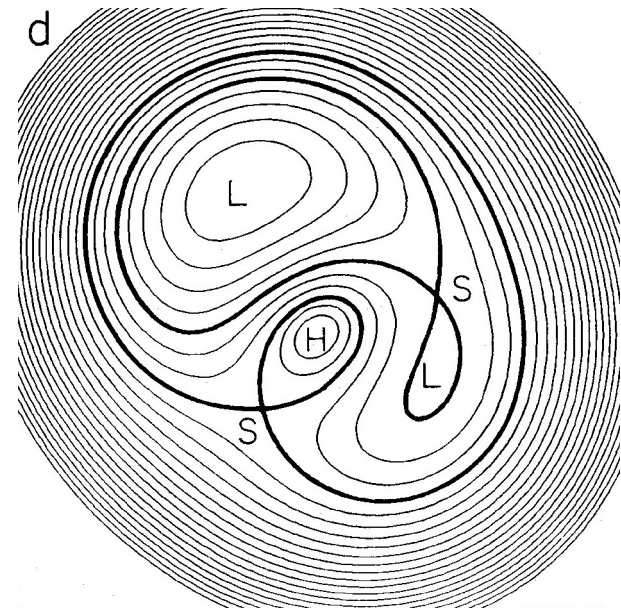
Ordinary ( $\det A \neq 0$ ) images occur at  $\nabla\tau(\boldsymbol{\theta}; \boldsymbol{\beta}) = 0$   
i.e., images are local extrema or saddles of Fermat surface  
(Fermat's Principle) for fixed  $\boldsymbol{\beta}$ . Note  $\tau_{ij} = A_{ij}$ .

## Image types:

Type I: minimum of  $\tau$   
 $\det A > 0$ ;  $\text{tr } A > 0$

Type II: saddle point of  $\tau$   
 $\det A < 0$

Type III: maximum of  $\tau$   
 $\det A > 0$ ;  $\text{tr } A < 0$



[Blandford & Narayan 1986]

For mass distributions of finite total mass and that are smooth, there will be at least one Type I image.

# Multiple Images

Question:

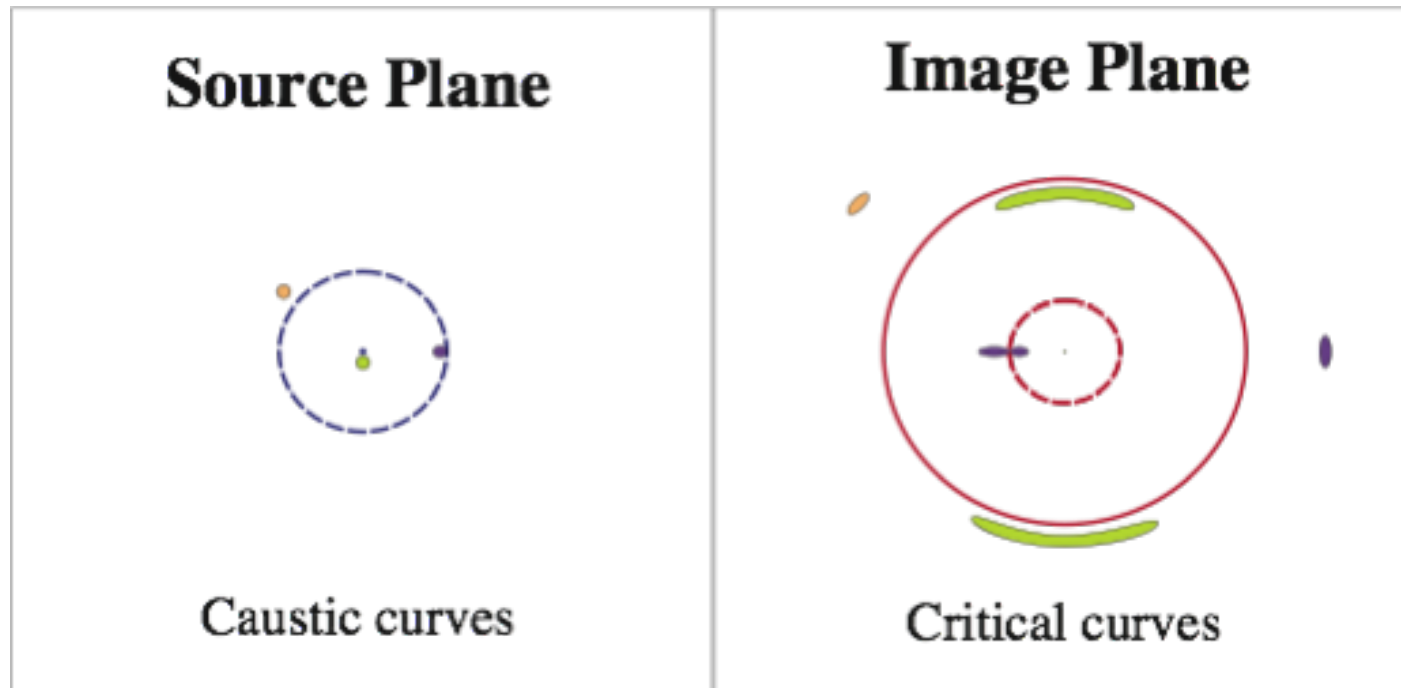
Given a lens mass distribution that is smooth with  $\det A > 0$  everywhere, what is the highest number of lensed images of a background source?

- 1) 1
- 2) 2
- 3) 3
- 4) 4
- 5) Unlimited, depending on the precise form of the lens mass distribution

# Critical curves and caustics I

$\det A = 0$ : critical curves on image plane  $\theta$   
corresponds to caustics on source plane  $\beta$







Example: non-singular isothermal sphere lens  $\rho(r) = \frac{\rho_0}{r_c^2 + r^2}$



Credit: A. Amara & T. Kitching

# Critical curves and caustics II

Example: non-singular isothermal ellipsoid lens

	Einstein Cross	Cusp Caustic	Fold Caustic
Source Plane			
Image Plane			

# Critical curves and caustics III

source plane  
caustics

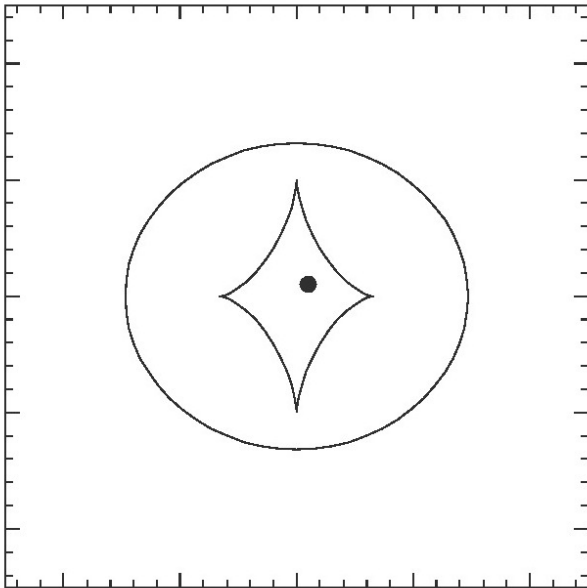


image plane  
critical curves

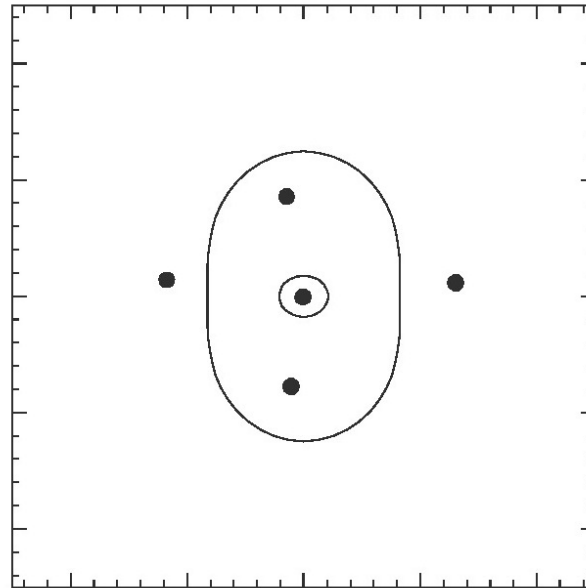
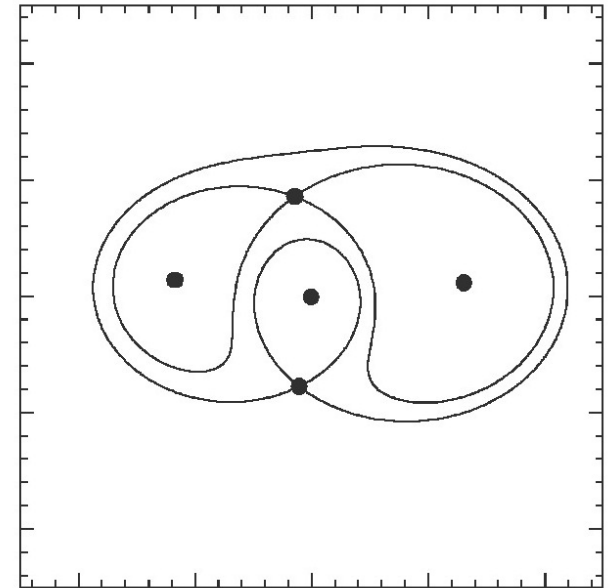


image plane  
time-delay contours



[Courbin et al. 2002]

# Critical curves and caustics IV

source plane

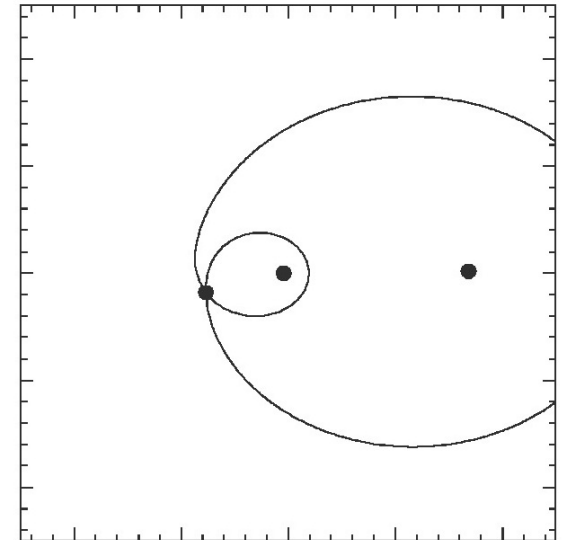
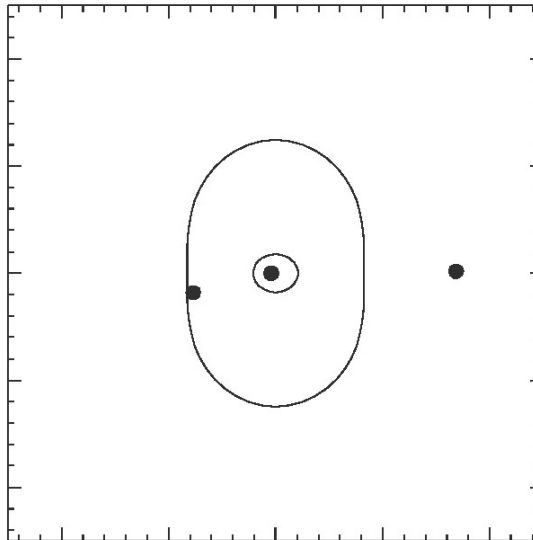
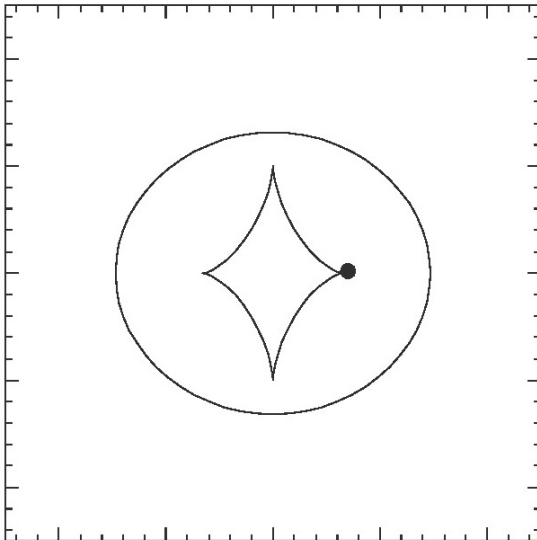
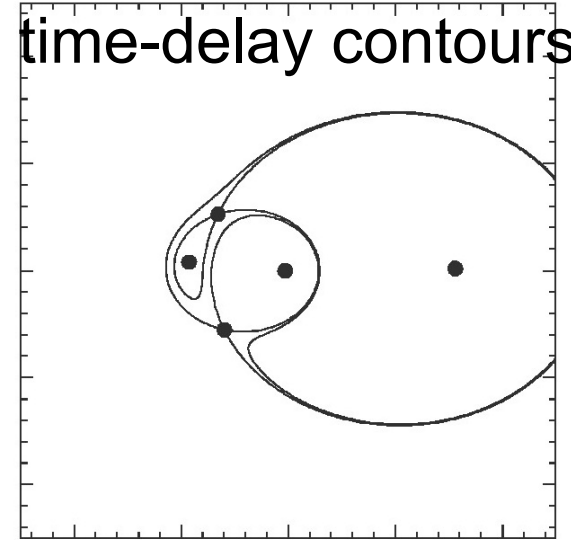
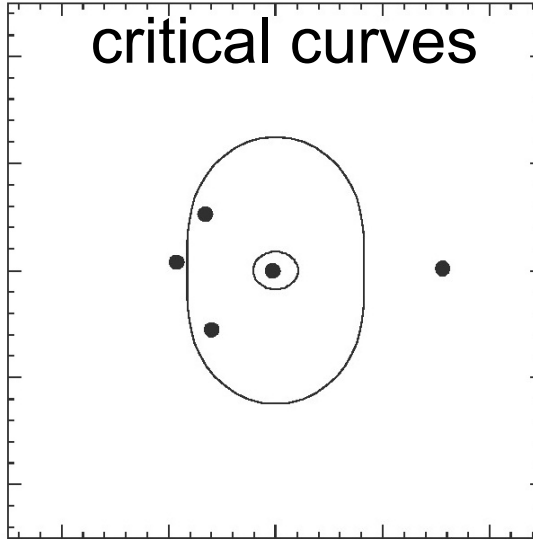
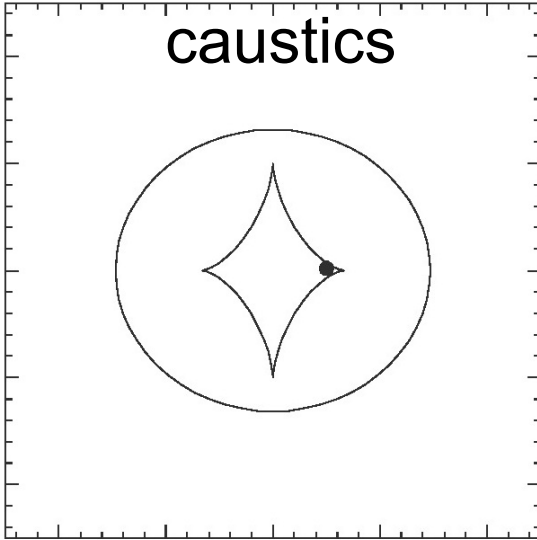
image plane

image plane

caustics

critical curves

time-delay contours



[Courbin et al. 2002]

# Critical curves and caustics V

source plane

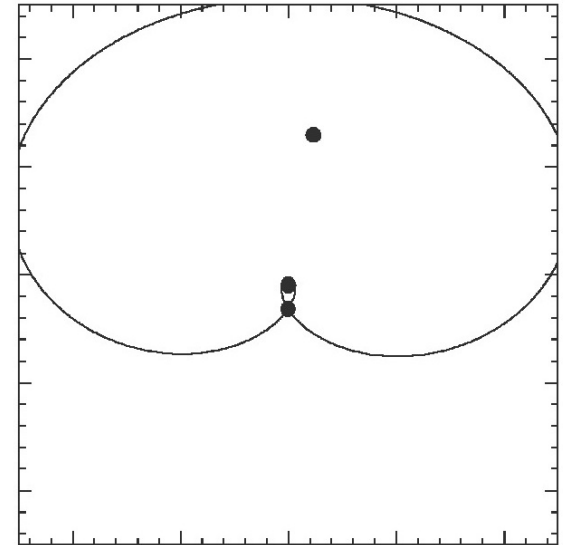
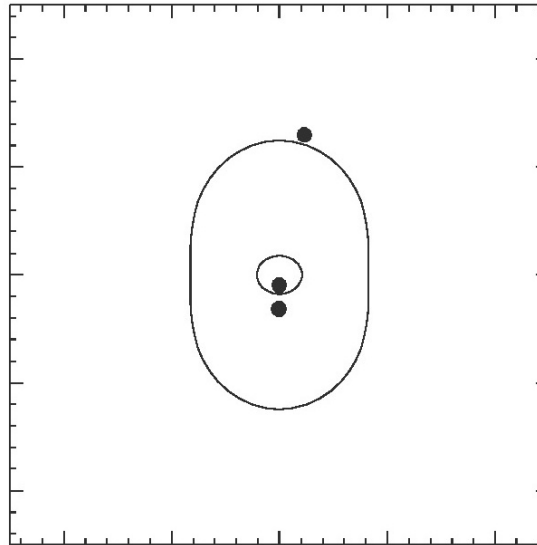
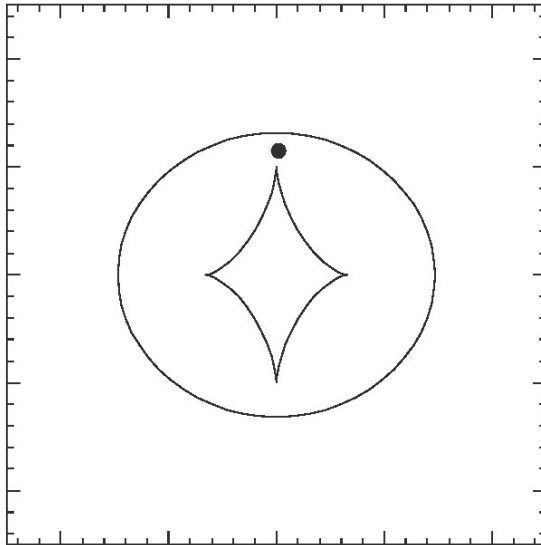
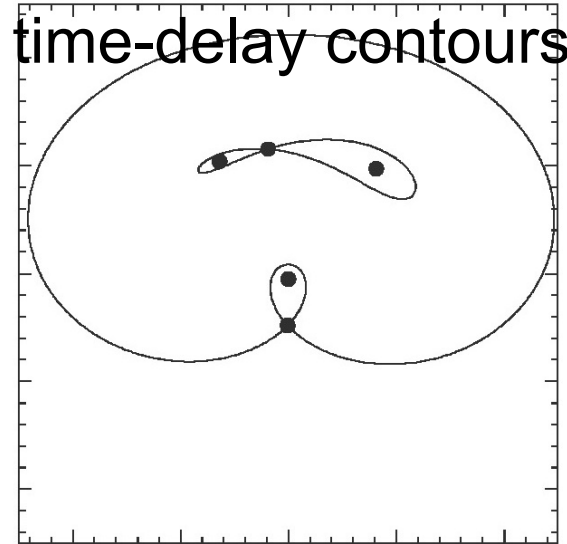
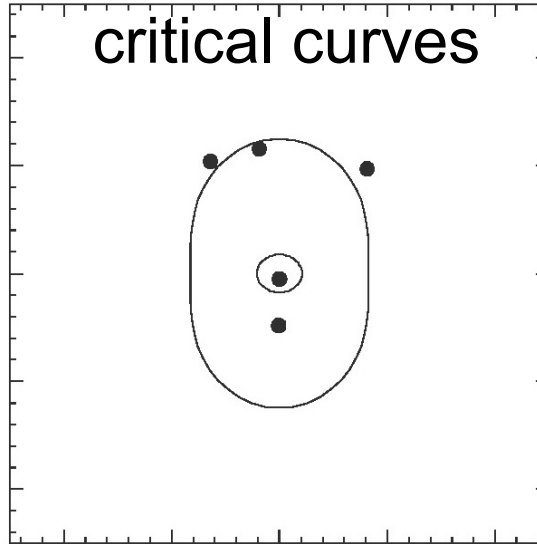
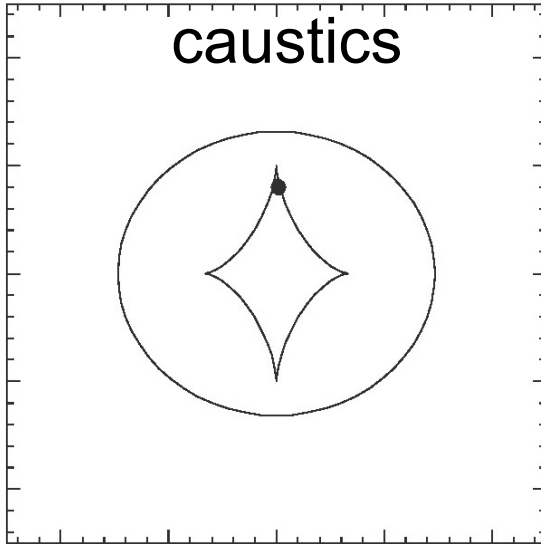
image plane

image plane

caustics

critical curves

time-delay contours



[Courbin et al. 2002]

# Critical curves and caustics VI

source plane

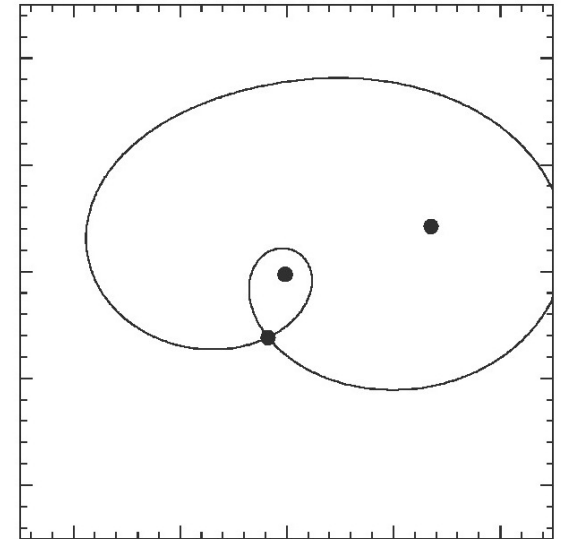
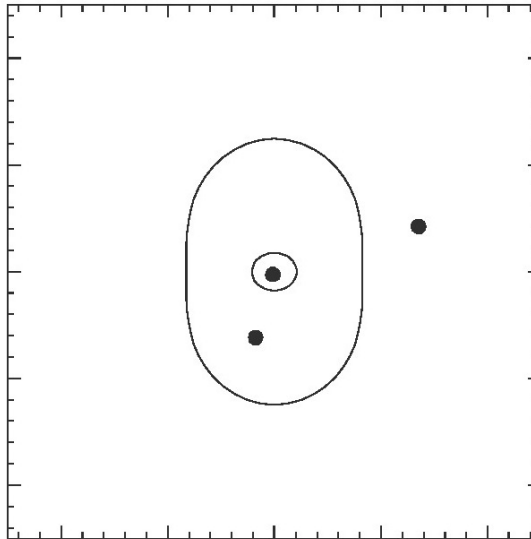
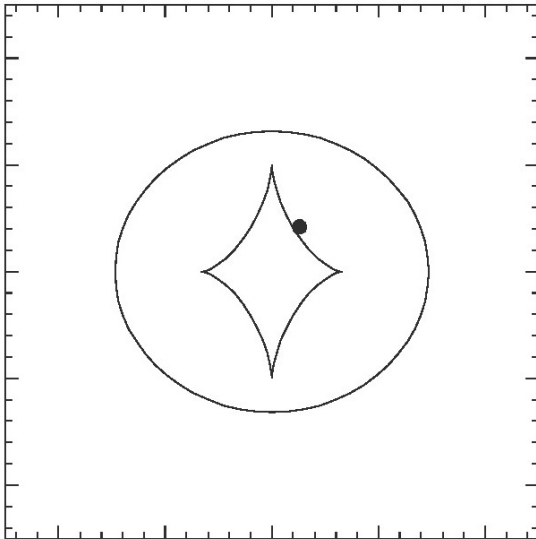
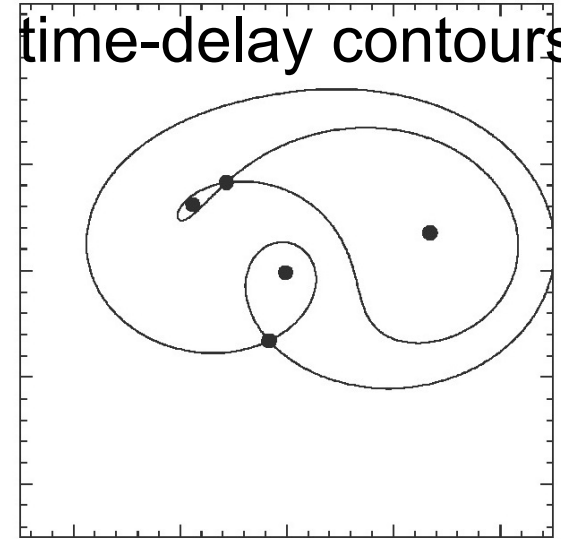
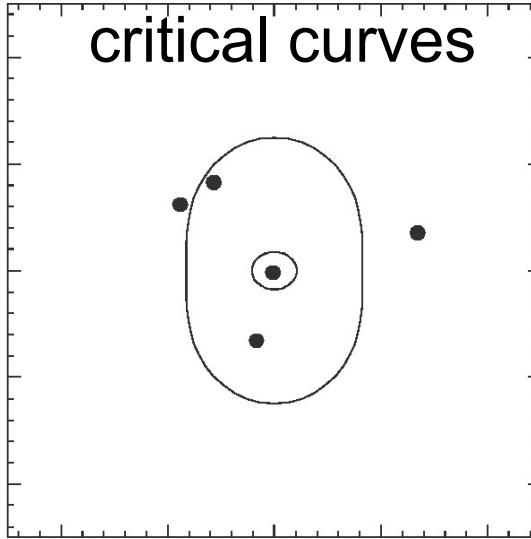
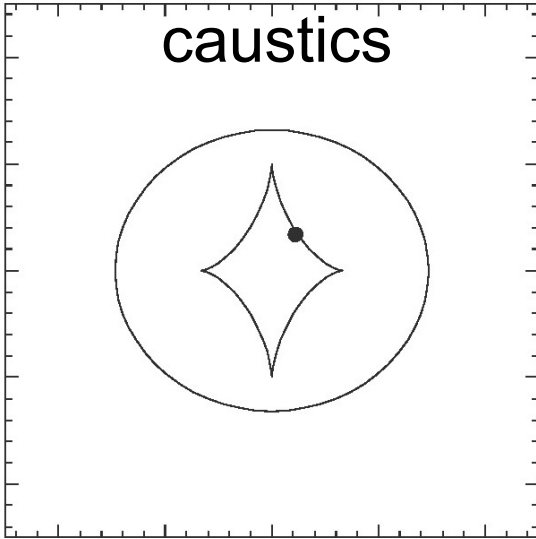
image plane

image plane

caustics

critical curves

time-delay contours

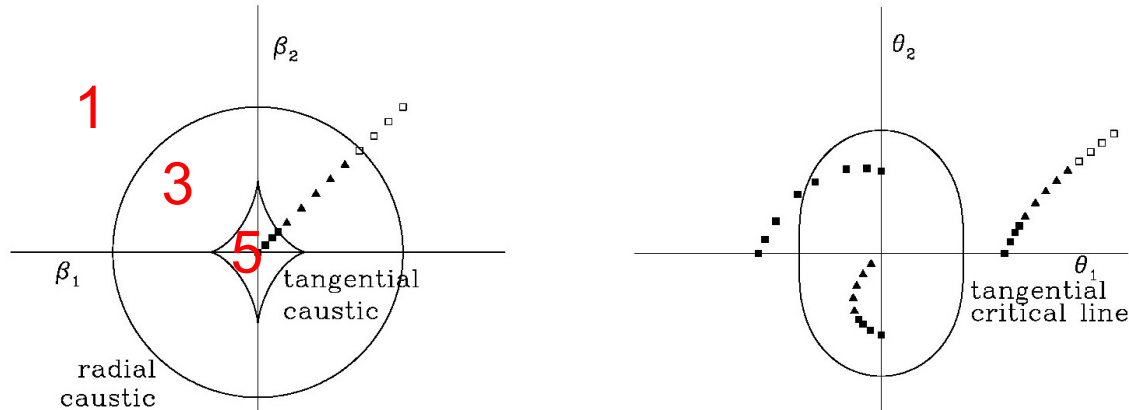


[Courbin et al. 2002]



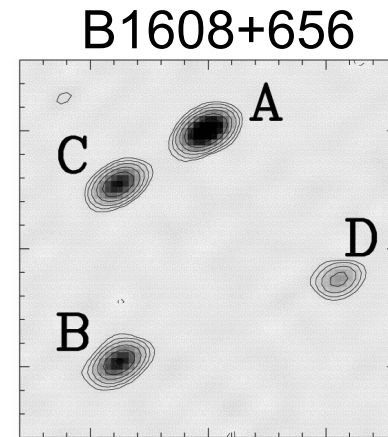
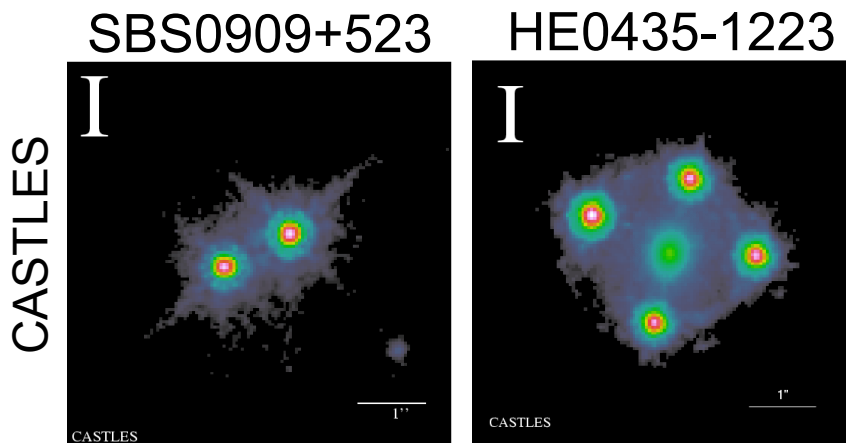
# Critical curves and caustics VII

Caustics separate regions of different image multiplicity



[Image credit:  
C. Kochanek]

Why do we typically find only 2 or 4 images in real lens systems? *Ans.: central image is demagnified*

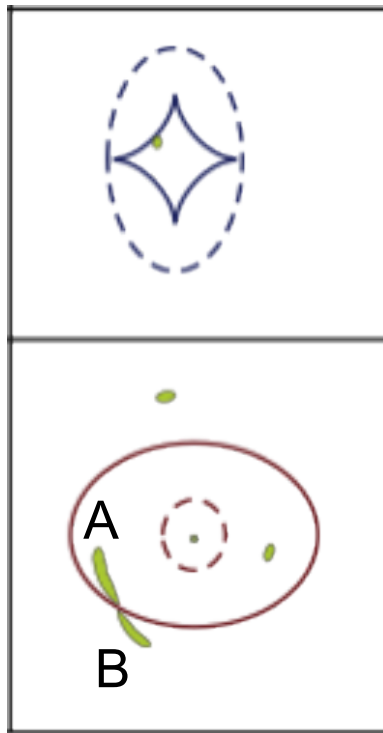


[Fassnacht et al. 2002]

# Cusp and fold relations

For smooth mass distribution:

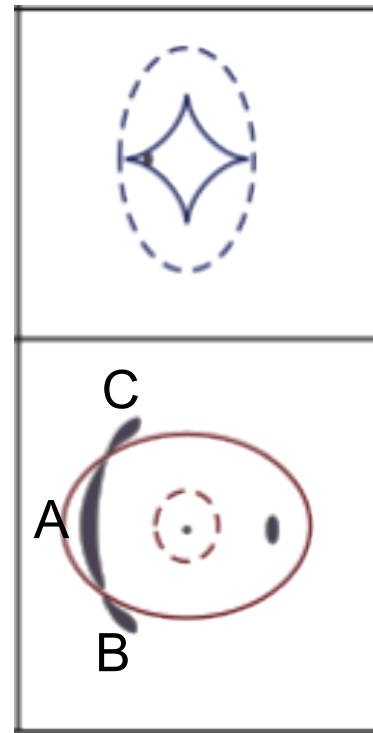
Fold relation



$$\mu_A + \mu_B = 0$$

$$|\mu_A| = |\mu_B|$$

Cusp relation



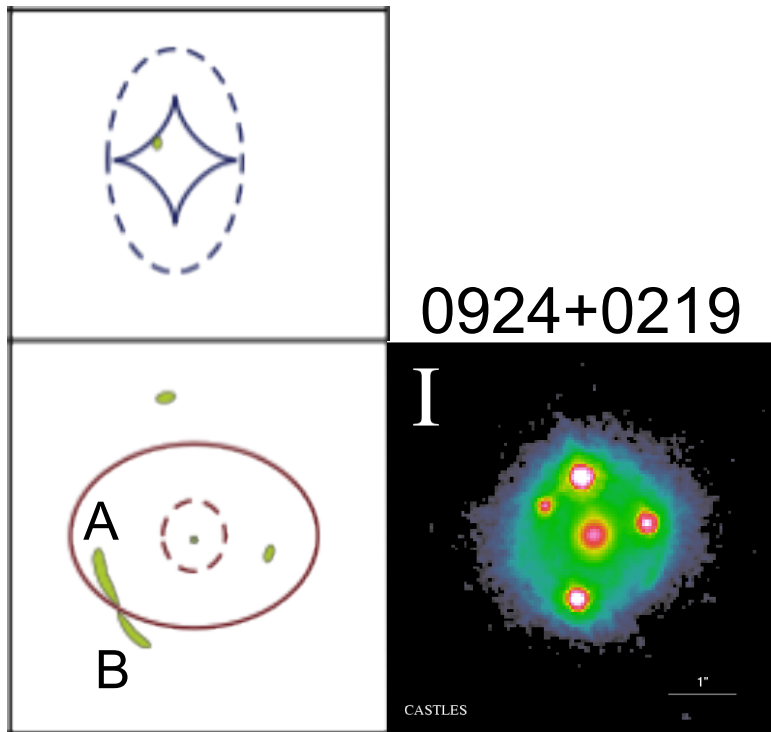
$$\mu_A + \mu_B + \mu_C = 0$$

$$|\mu_A| = |\mu_B| + |\mu_C|$$

# Observed cusp and fold lenses

For smooth mass distribution:

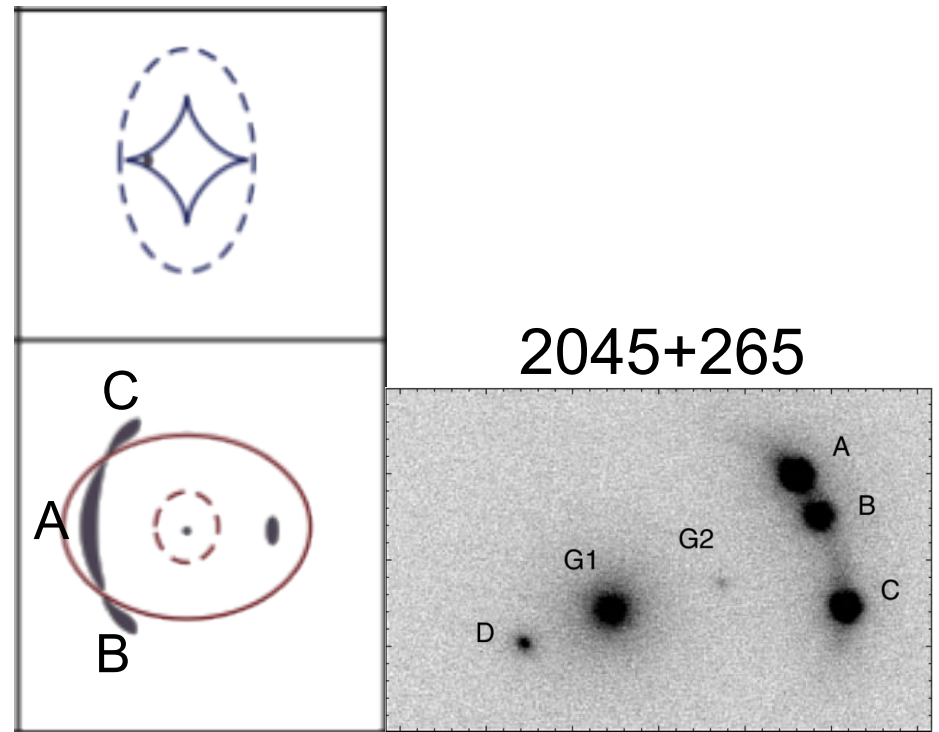
## Fold relation



$$\mu_A + \mu_B = 0$$

$$|\mu_A| = |\mu_B|$$

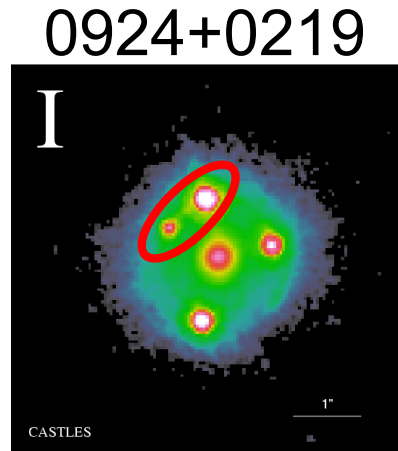
## Cusp relation



$$\mu_A + \mu_B + \mu_C = 0$$

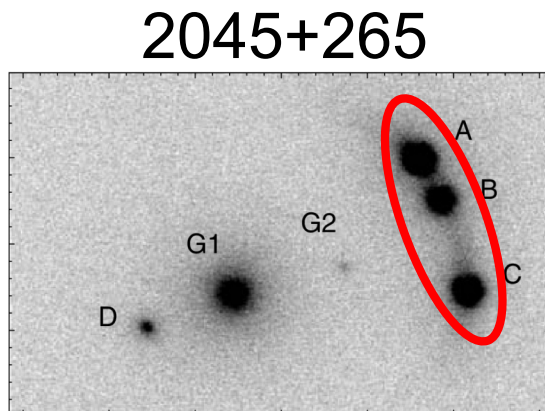
$$|\mu_A| = |\mu_B| + |\mu_C|$$

# Violations of cusp and fold relations



*What causes the violations?*

- time delays (variability)
- dust extinction
- microlensing
- substructure



*By eliminating the first three causes, lensing provides a unique way to detect dark matter substructure*