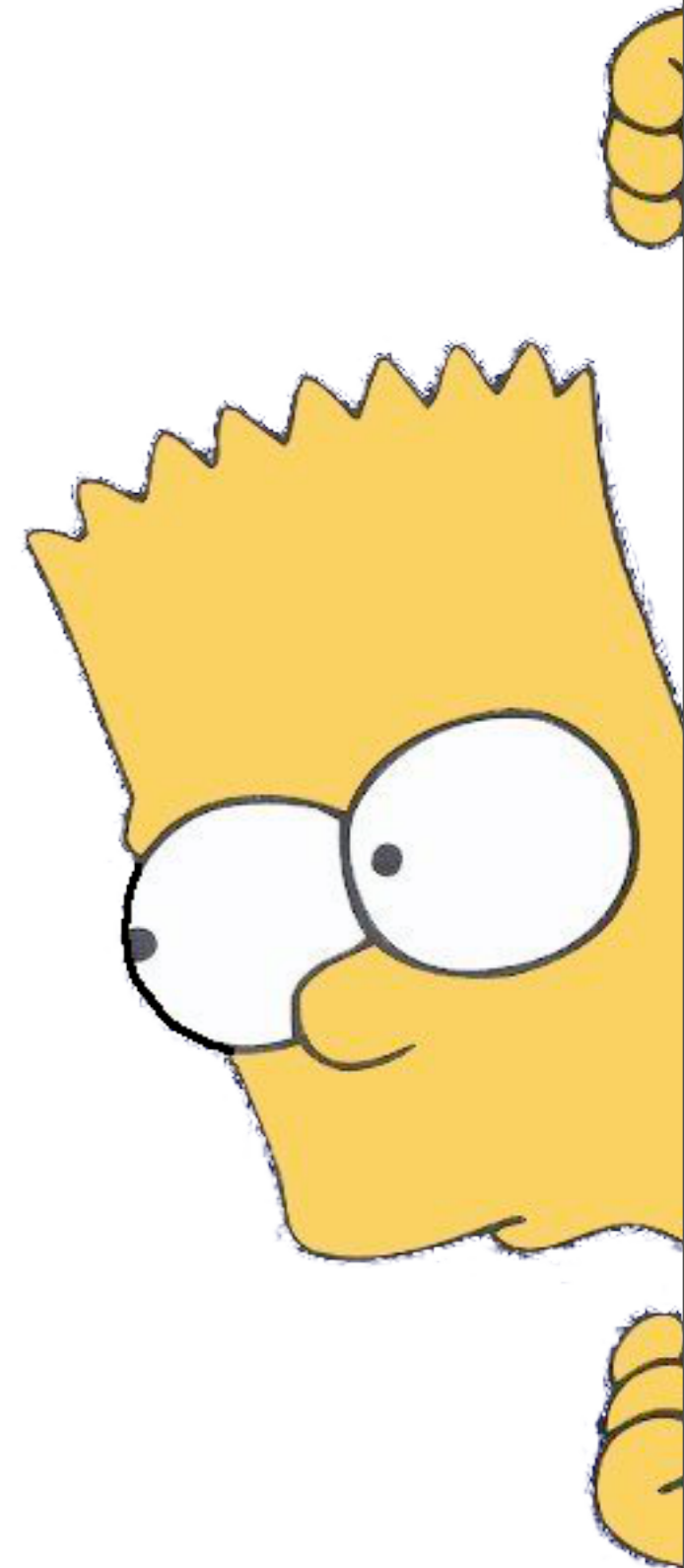


Bayesian Analysis for the Ranking of Transits

Olivier Demangeon
Pascal Bordé, Marc Ollivier, Alain Léger



Layout

I. What is BART and what are its objectives ?

II. Description of BART

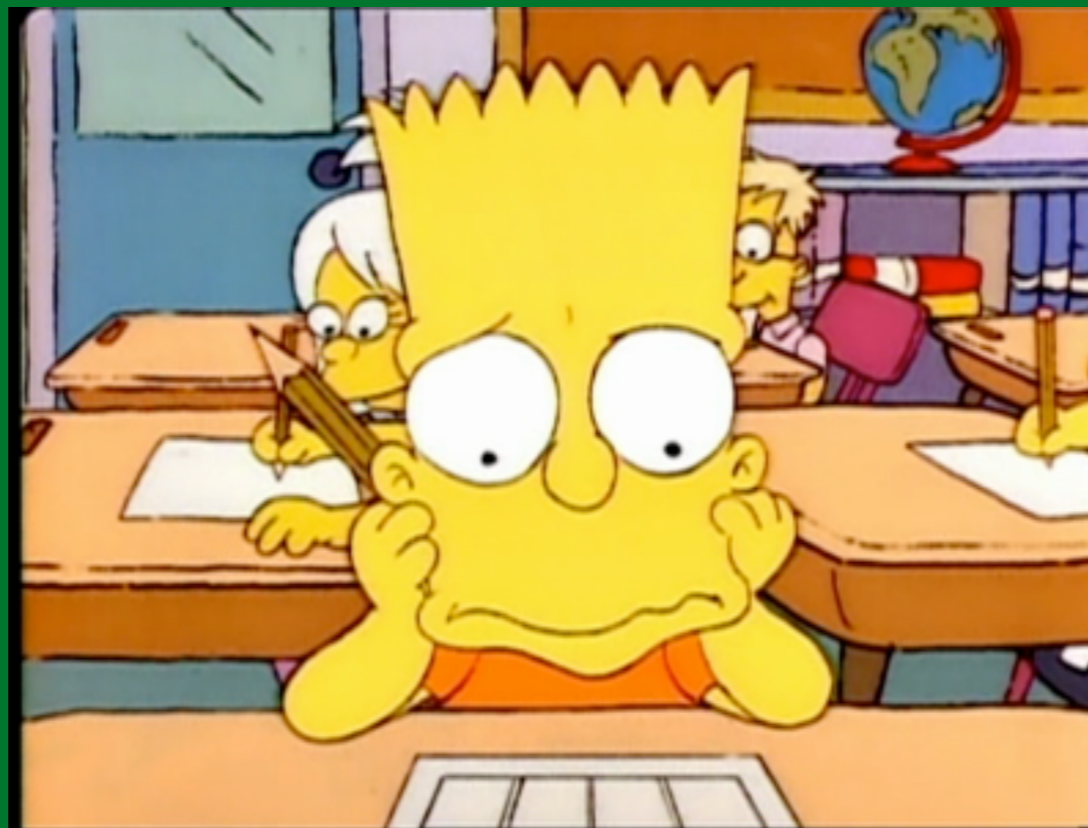
III. Current results

IV. Conclusions and outlooks



I. What is BART and what are its objectives ?

I.1) Issues



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- The follow-up observations **requires lots of time, money and man-power**. CoRoT-7b : 70h (100 nights) on HARPS;
- Most targets with **magR > 15 ~ 16** can't be **followed** (especially in RV).
- Probabilistic validation (BLENDER, PASTIS) is a **long** (computer time) **and complex task** (CoRoT-22b).

1.2) Objectives of BART



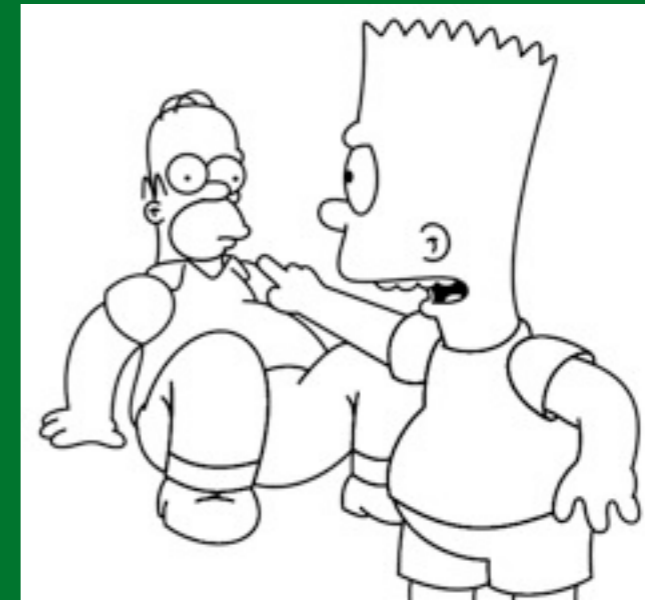
1.2) Objectives of BART

Link between detection and follow-up teams

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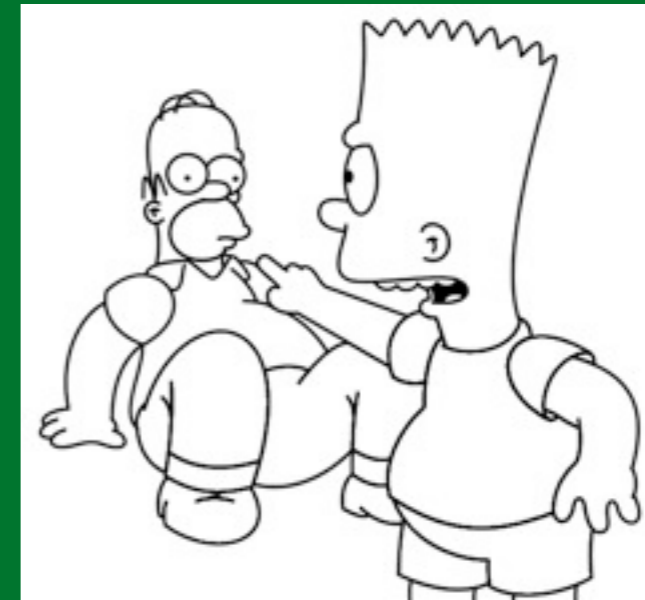
- Point at the most promising transits for follow-up observations and probabilistic validation;



1.2) Objectives of BART

Link between detection and follow-up teams

- **Point at the most promising transits** for follow-up observations and probabilistic validation;
- Make a **report** on what we can **infer with the light curve alone** on each transit.



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- Produce a **ranking** of transit based on the probability of each transit to be PS;
- Use **bayesian inference of parameters** to obtain the probability density function of all the parameters (density, radius ratio, ...) of all the scenari (PS, EB, ...)

II) Description of BART

II.1) Bayesian model comparison

Posterior probability Likelihood Prior probability

$$\Pr(M|d, I) = \frac{\Pr(d|M, I) \Pr(M|I)}{\Pr(d|I)}$$

Marginalized likelihood (Normalization factor)

M : model (PS, EB, CEB ...)
d : data
I : context of the measurement

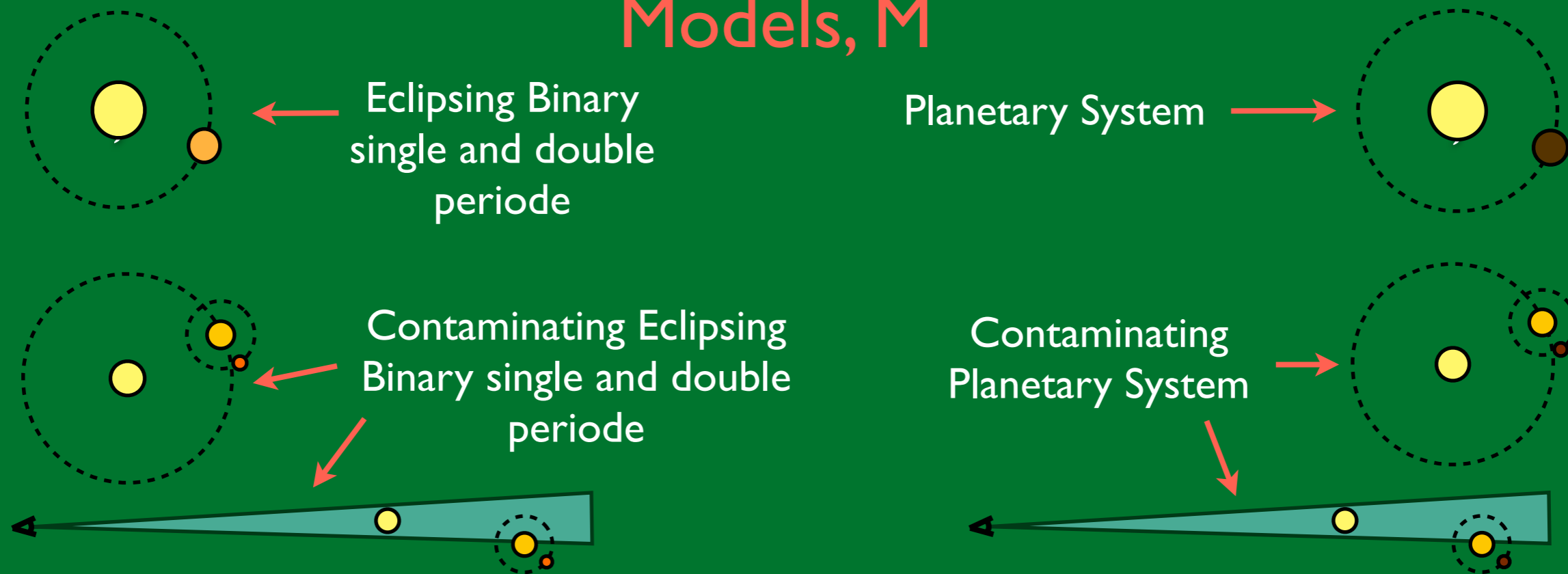
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Posterior probability (points to $\text{Pr}(M|d, I)$)
 Likelihood (points to $\text{Pr}(d|M, I)$)
 Prior probability (points to $\text{Pr}(M|I)$)
 Marginalized likelihood (Normalization factor) (points to $\text{Pr}(d|I)$)

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Models, M



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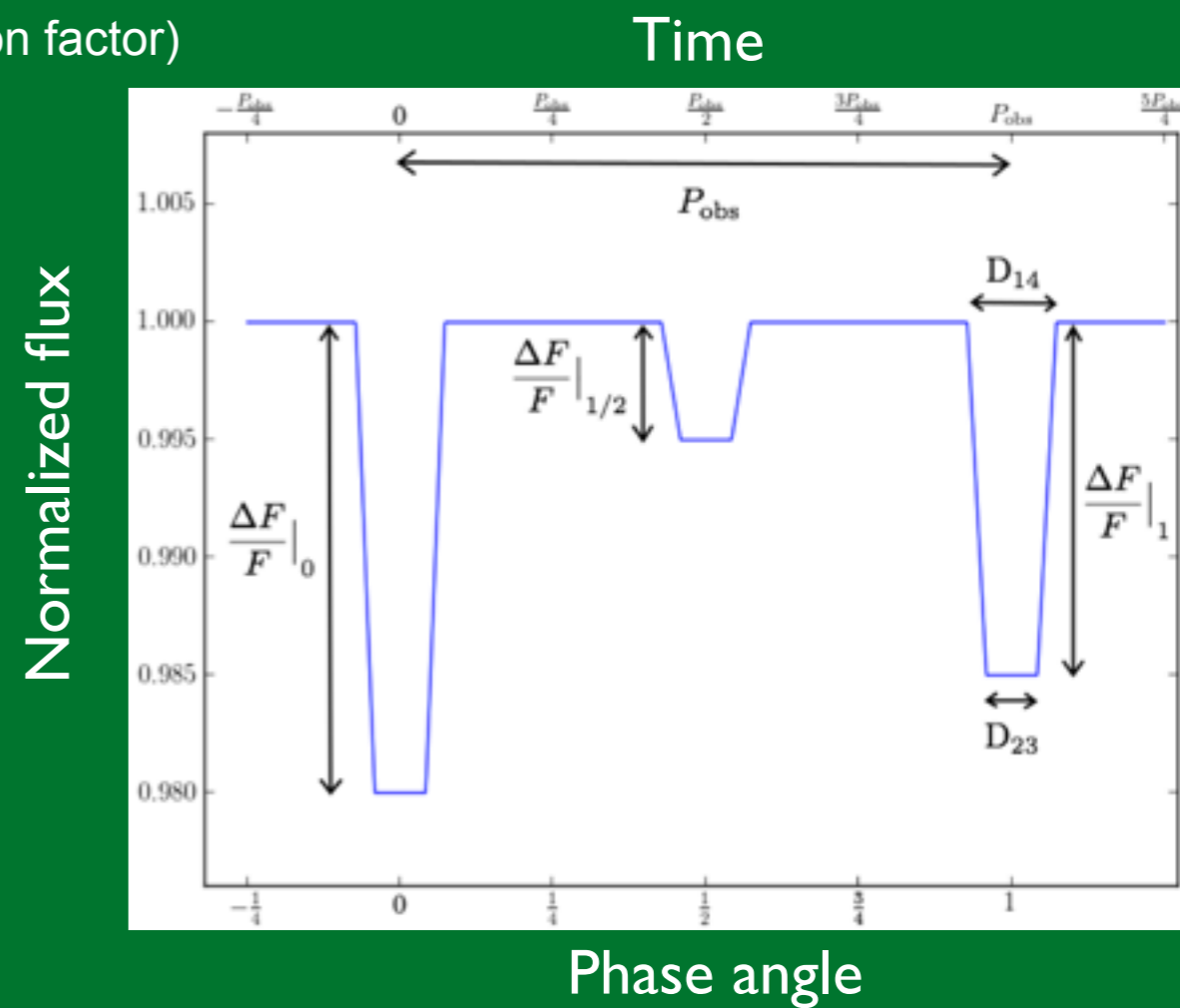
$$\text{Pr}(M|d, I) = \frac{\text{Pr}(d|M, I) \text{Pr}(M|I)}{\text{Pr}(d|I)}$$

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Data, d

To take advantage of the work done by the detection teams, I use as data measured on the transit



II.2) Bayesian inference parameters

Posterior probability density Likelihood Prior probability density

$$p(\boldsymbol{\theta}|d, M, I) = \frac{p(d|\boldsymbol{\theta}, M, I) p(\boldsymbol{\theta}|M, I)}{p(d|M, I)}$$

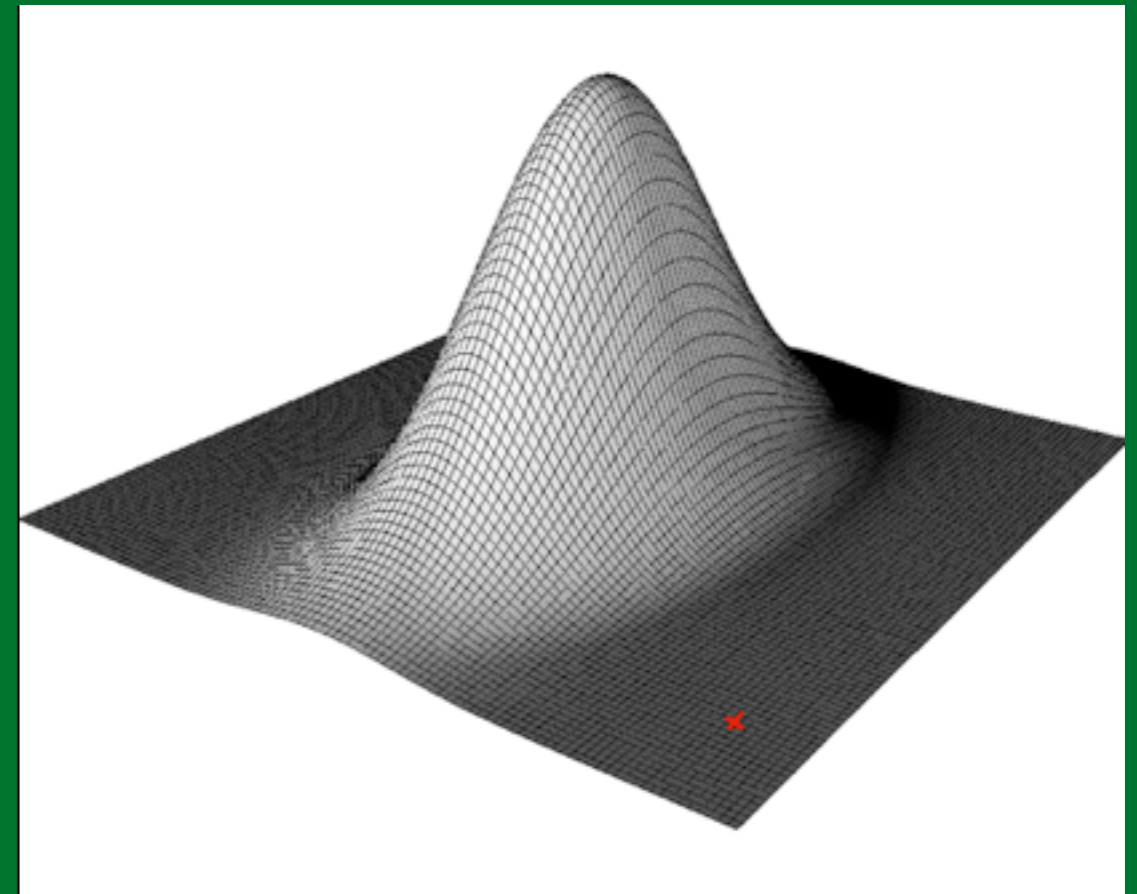
$\boldsymbol{\theta}$: Parameters

Marginalized likelihood
(Normalization factor)

PS	CPS	EB (P, 2P)	CEB (P, 2P)
• b impact parameter	• b impact parameter	• b impact parameter	• b impact parameter
• $\frac{R_{pl}}{R_{st}}$ radius ratio	• $\frac{R_{pl}}{R_{st}}$ radius ratio	• $\frac{R_{prim}}{R_{sec}}$ radius ratio	• $\frac{R_{prim}}{R_{sec}}$ radius ratio
• ρ_{st} stellar density	• ρ_{st} stellar density	• ρ_{som} system density	• ρ_{som} system density
• P orbital periode	• P orbital periode	• P orbital periode	• P orbital periode
	• C contamination factor	• $\frac{T_{prim}}{T_{sec}}$ effective temperature ratio	• $\frac{T_{prim}}{T_{sec}}$ effective temperature ratio
		$\rho_{som} = \frac{M_{prim} + M_{sec}}{4/3\pi R_{prim}^3}$	• C contamination factor

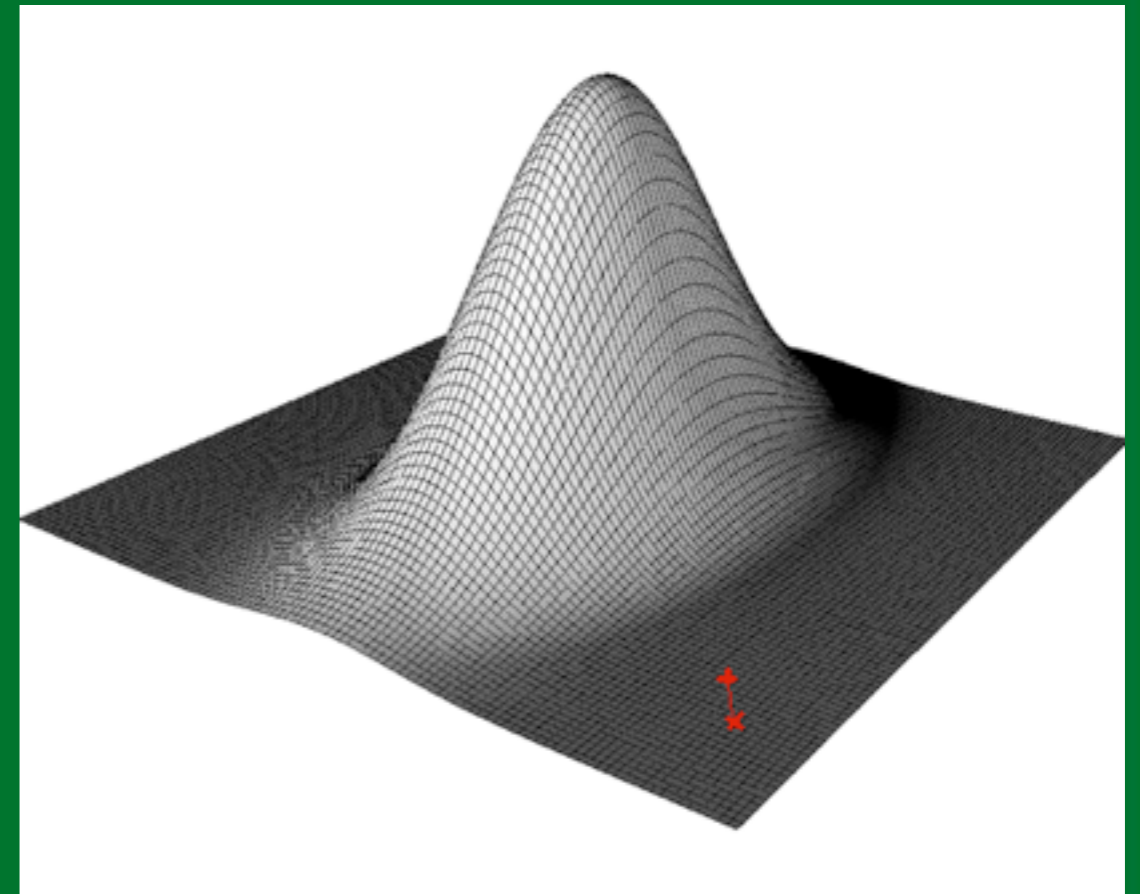
II.3) Exploration of parameter space and integration

- Fasten execution time :
MCMC exploration
Monte carlo integration
- Automatisation : **Personal adaptation** of P.C. Gregory (2005)
Adaptative Metropolis-Hasting algorithm (acceptance rate and trace correlation feedback) **more efficient with correlated parameters**



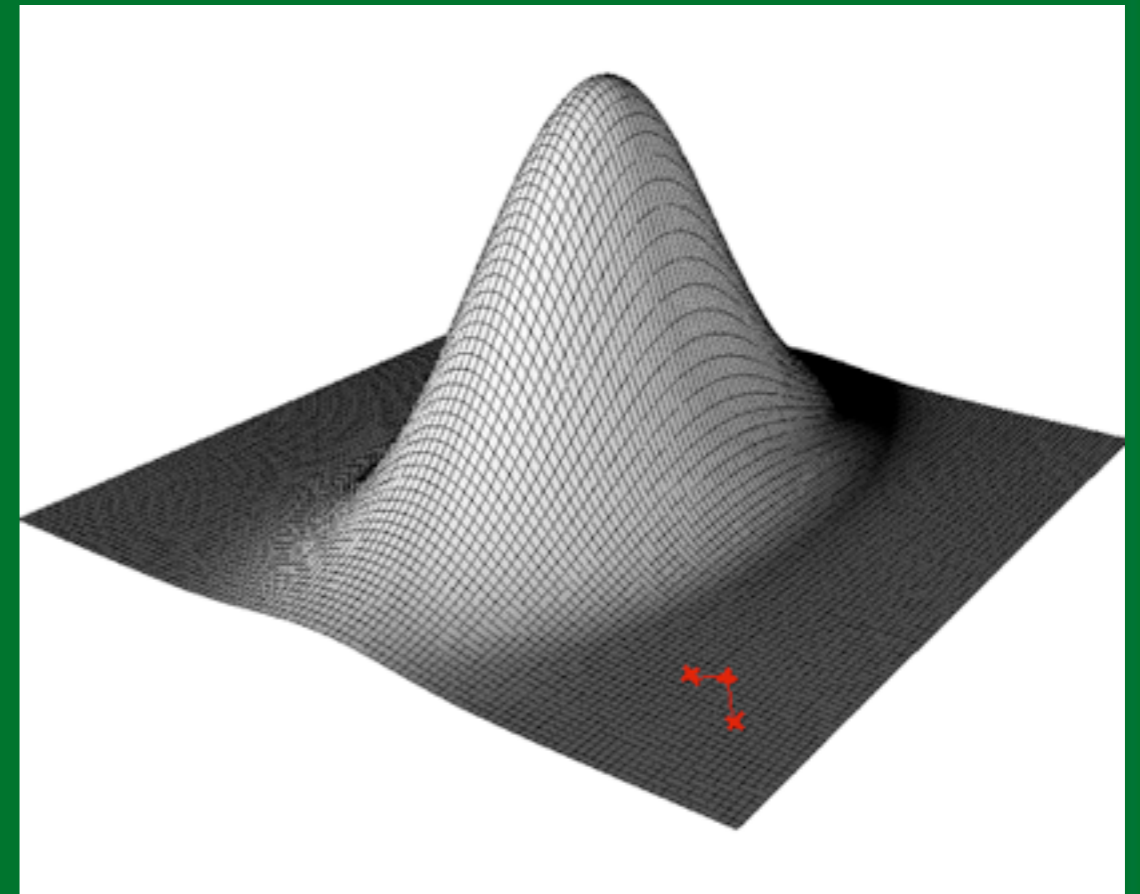
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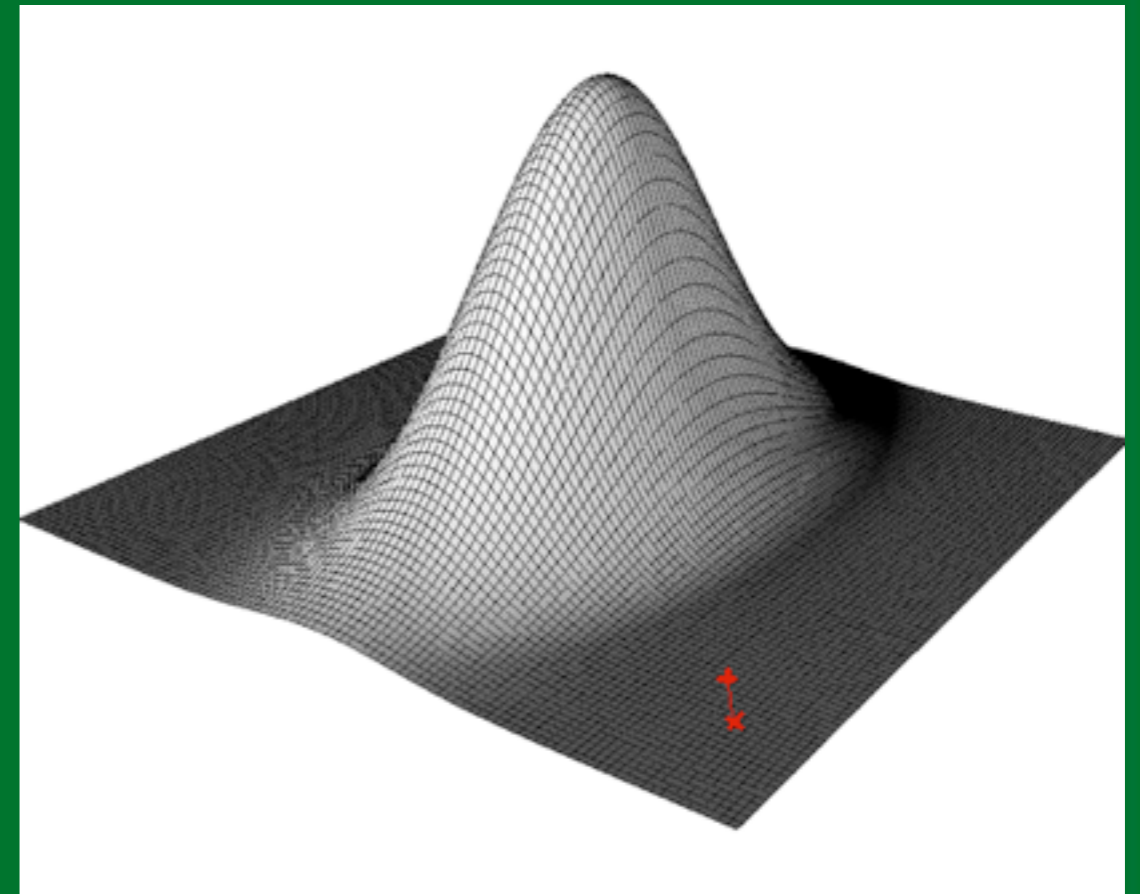
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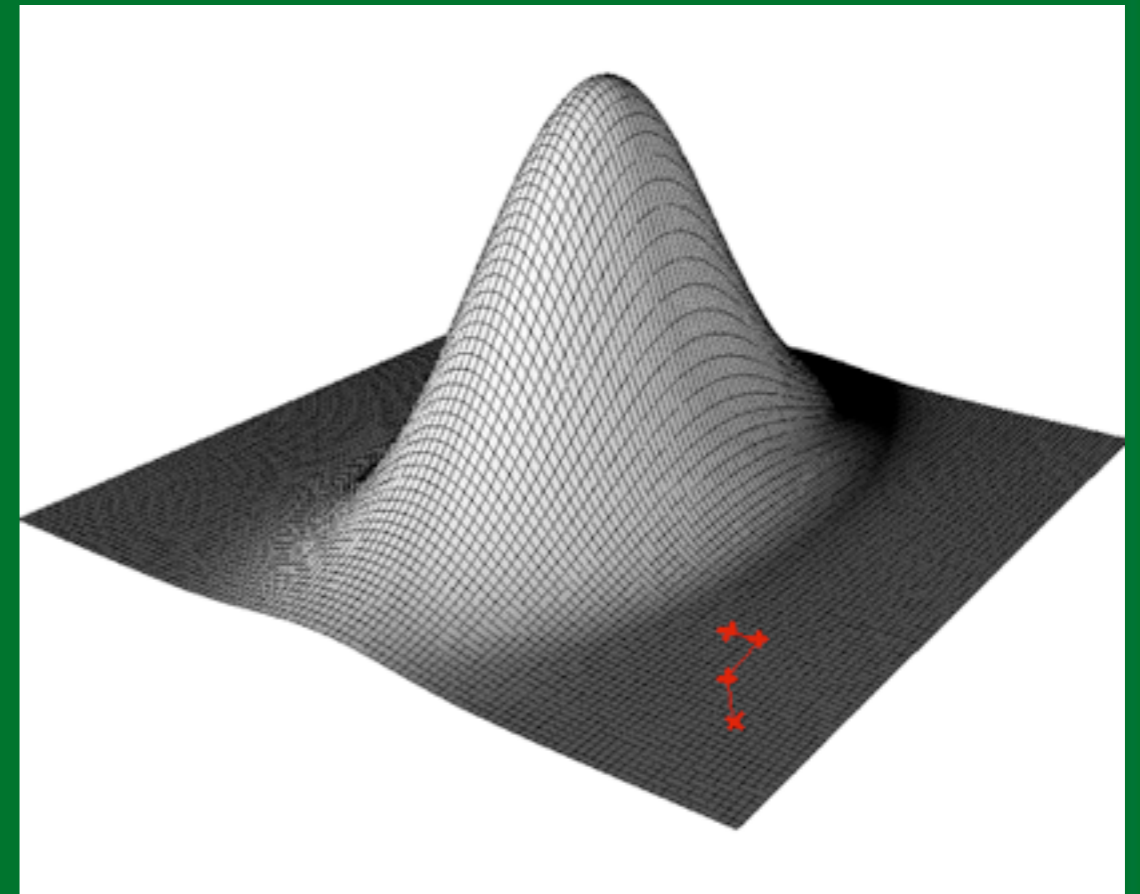
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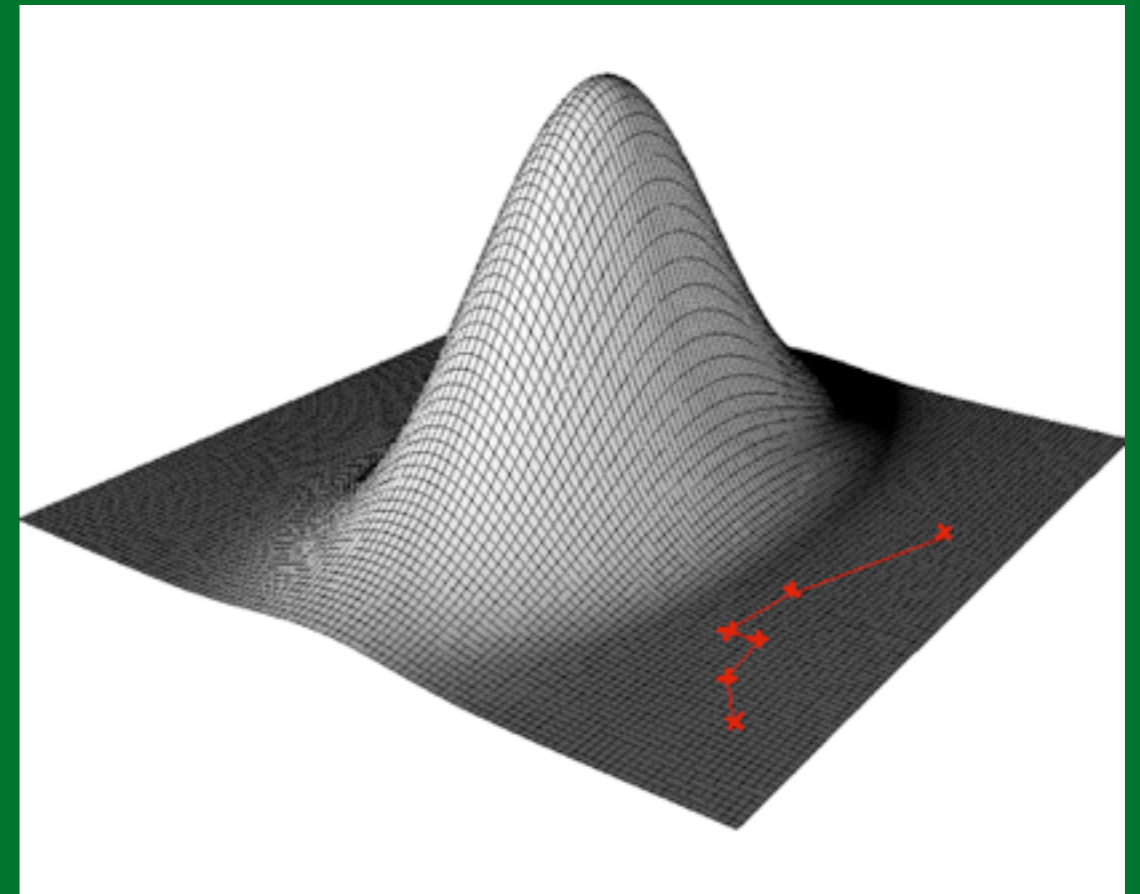
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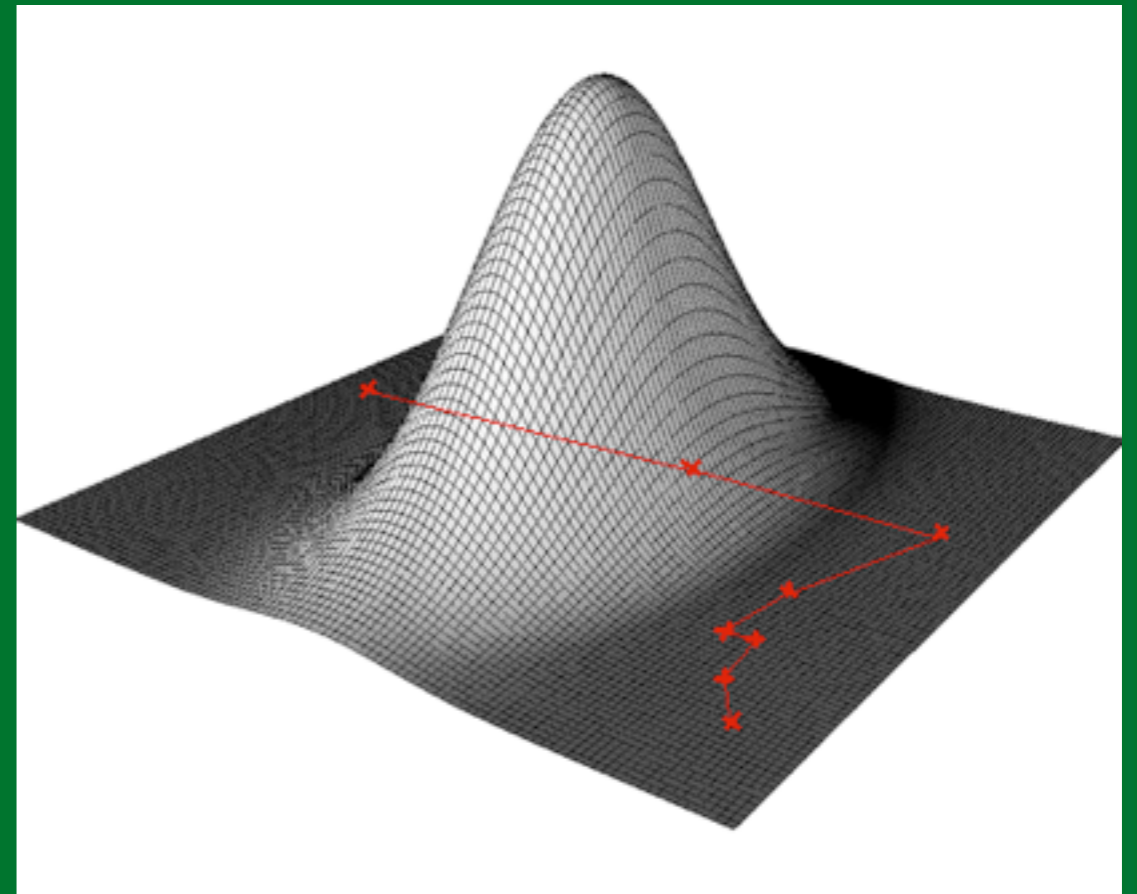
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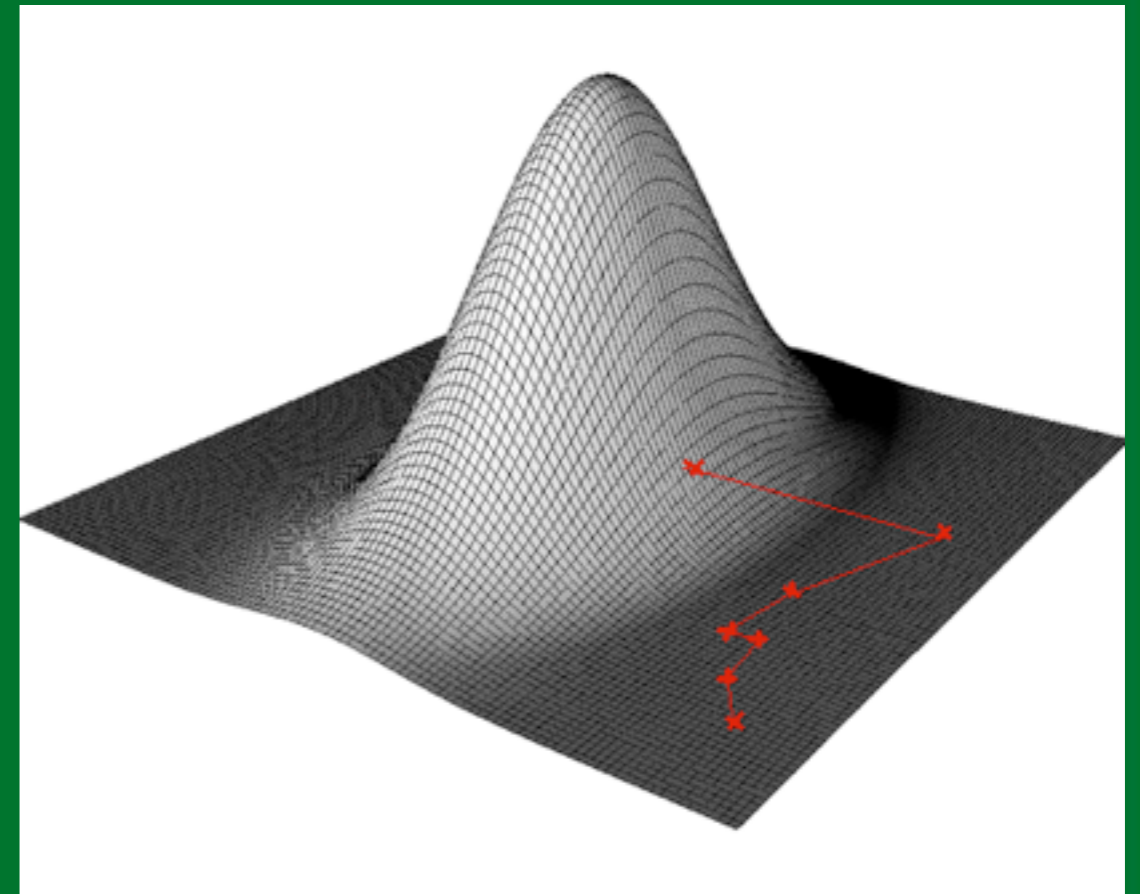
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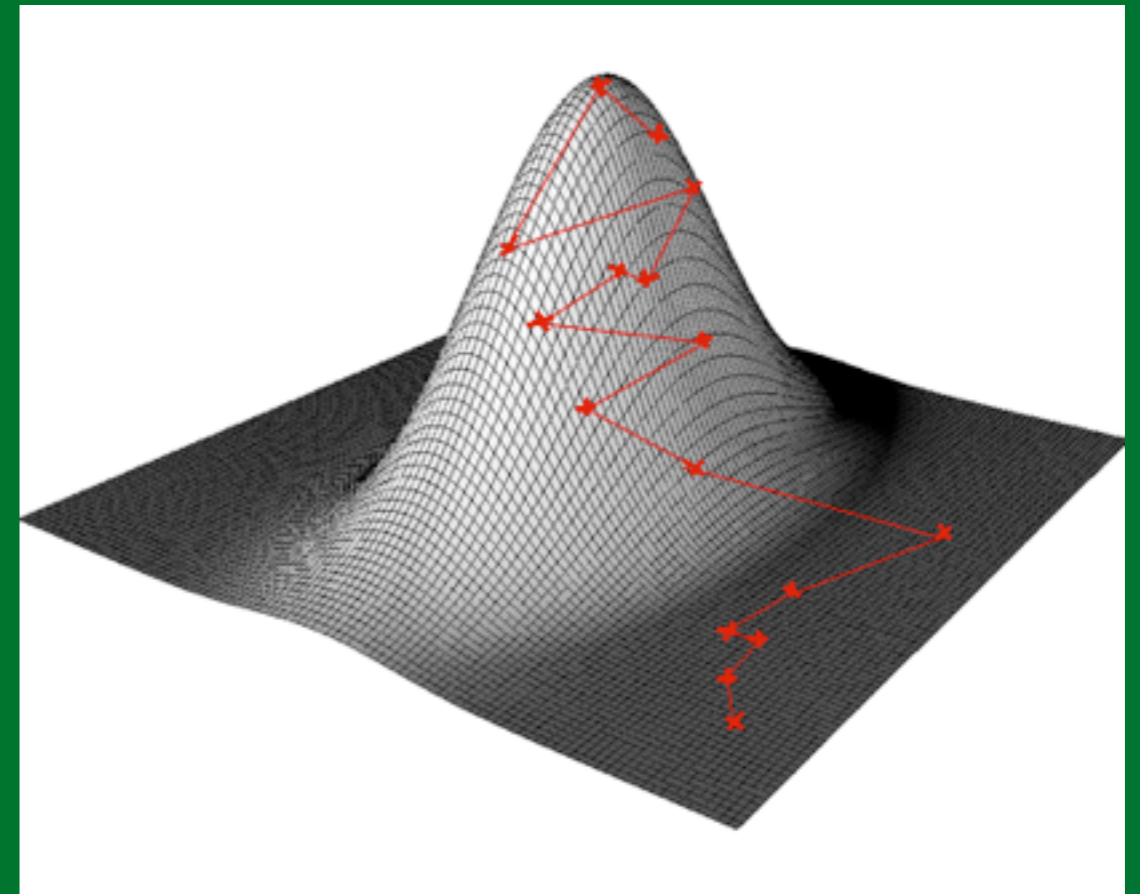
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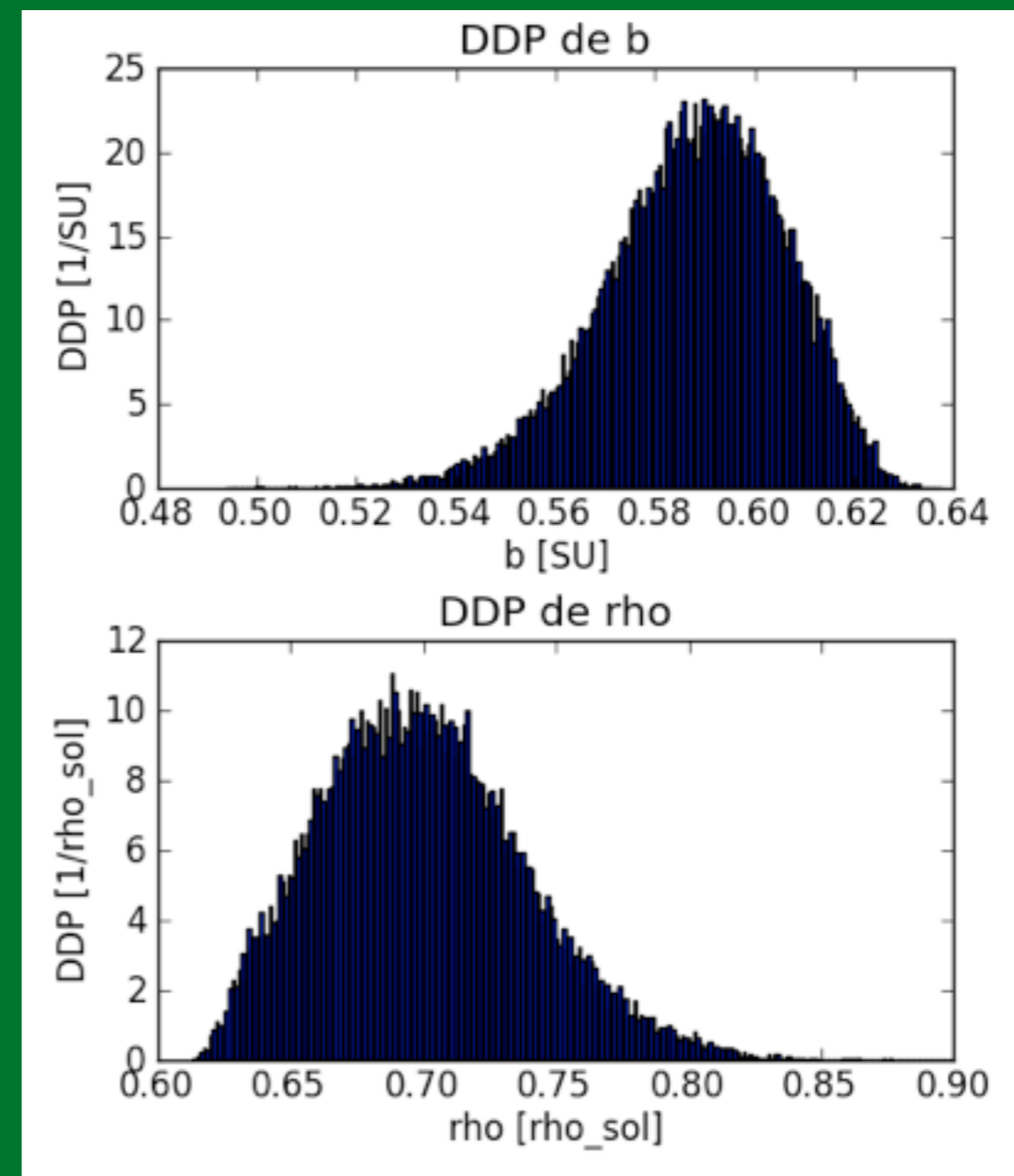
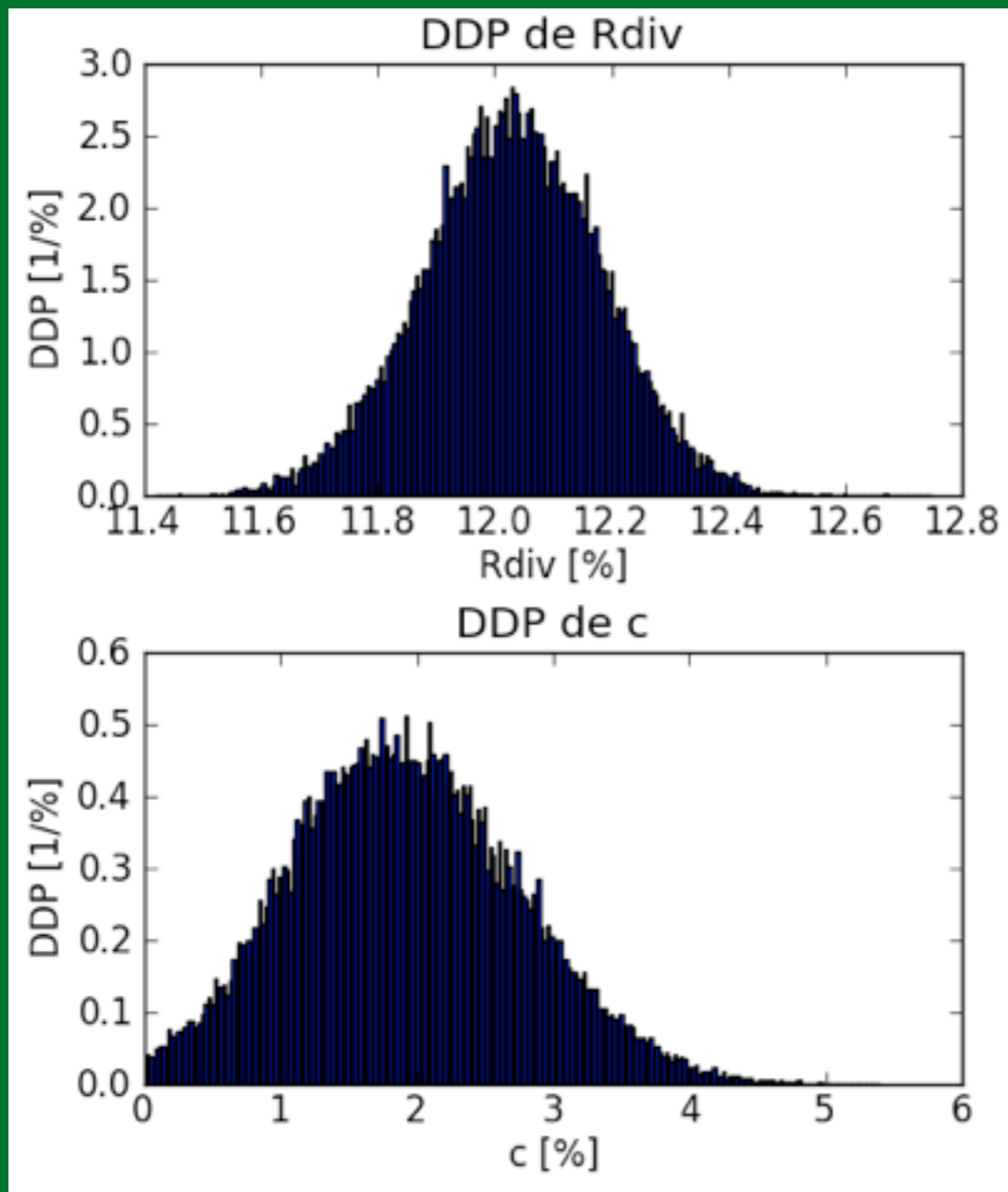
III) Current results

III.1) Current results : Ranking of 22 candidates from LRc02

Rank	Candidate	PS Probability (without Exodat Density prior)	Nature (Wiki CoRoT)	Nature (My tool)
1	LRc02-E1R-632	9,98E+01	PS (CoRoT-6b)	PS
2	LRc02-E1L-249	9,98E+01	P3 (Slightly chromatic)	PS
3	LRc02-E1R-1280	9,95E+01	PS (CoRoT-25b)	PS
4	LRc02-E2R-4630	9,93E+01	P1 (Faint but nice candidate)	PS
5	LRc02-E1L-3424	1,07E-02	P3 (Conflict with Exodat density)	CPS
6	LRc02-E1R-3179	6,09E-03	P3 (Conflict with exodat density)	CEBP
7	LRc02-E1L-2870	5,54E-04	CEBP (Highly colored)	EBP
8	LRc02-E1L-3654	2,63E-06	P3 (Significant Odd/Even transit depth)	CEB2P
9	LRc02-E2R-293	3,83E-07	CEB (Highly Chromatic)	CPS
10	LRc02-E1R-591	6,24E-12	PS (CoRoT-22b)	CEBP
11	LRc02-E1L-202	4,05E-15	PS (CoRoT-11b)	CPS
12	LRc02-E1L-981	3,92E-35	SB1 (HARPS+McDonald)	EBP
13	LRc02-E1L-3088	6,69E-45	P2 (Conflict with Exodat density)	CPS
14	LRc02-E1L-1192	1,56E-46	CEB (Euler: likely CEB)	CPS
15	LRc02-E1R-483	4,19E-54	CEB (Sophie: 2pt, no var)	CEB2P
16	LRc02-E2R-2879	7,06E-58	P3 (Shape difference between Odd&Even)	CEBP
17	LRc02-E1L-1284	3,49E-110	P3 (Conflict with Exodat density+Several significant Contaminant)	CEB2P
18	LRc02-E2L-4747	6,44E-143	PS (CoRoT-26b)	CEBP
19	LRc02-E1R-136	3,25E-302	CEB (Sophie+HARPS+Highly Chromatic)	CEBP
20	LRc02-E1R-1427	0,00E+00	P3 (Phot:On-target, Period estimation issue)	CPS
21	LRc02-E1R-2282	0,00E+00	P3 (Conflict with exodat density+Odd/Even transit depth variation)	CEB2P
22	LRc02-E2L-2731	0,00E+00	P3 (Secondary eclipse seems to be there)	EBP

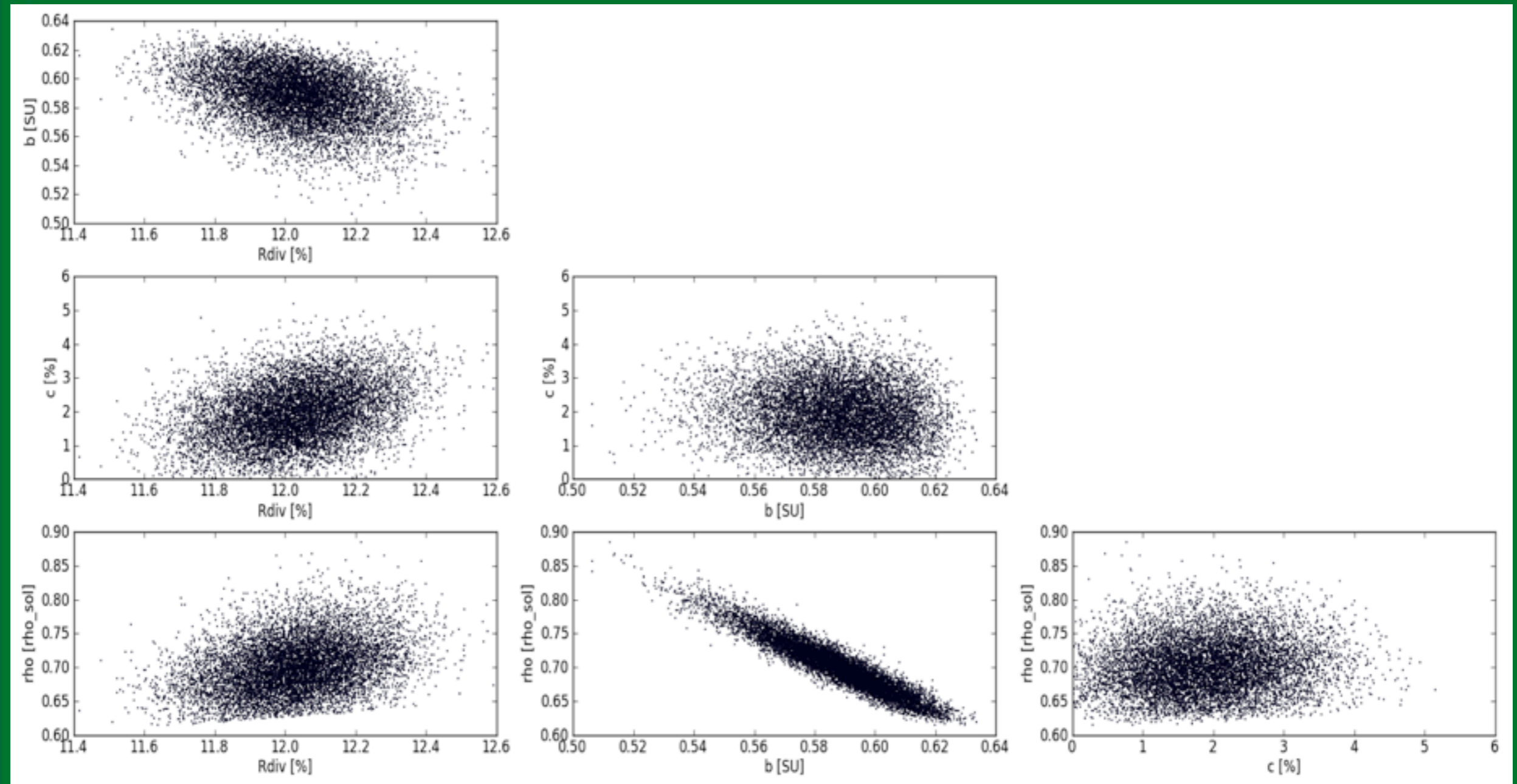
III.2) Current results : Parameters inference

CoRoT-6b -- PS



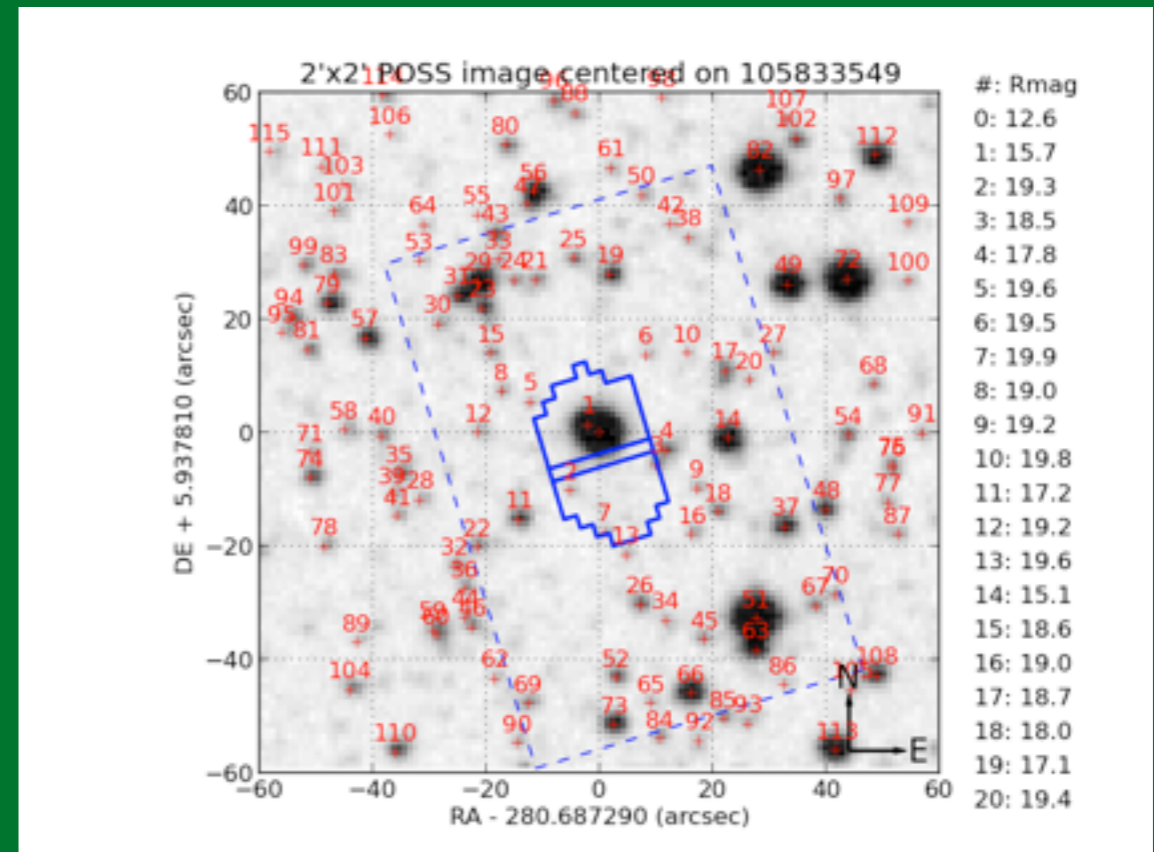
III.3) Current results : Correlation diagrams

CoRoT-6b -- PS



IV) Conclusions and outlook

- The ranking is **already quite good** (except for high impact parameter planets) ;
- I think that it could be even better with a **more detailed description of contamination** (contaminant list and colors);
- Development of more **detailed prior probabilities on models and parameters**



Thank you for attention !

