The Cosmic Web in Phase-Space



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Outline

- Collisionless fluids: the Vlasov-Poisson equation
- The Zel'dovich approximation
- Shell-crossing and caustics
- The dark matter phase-space sheet

Collisionless Fluids

Self-gravitating, collisionless system (e.g. distribution of dark matter) evolves via *Vlasov-Poisson* equations.

f = phase-space densitydistribution function $\phi = \text{gravitational potential}$ $\rho = \text{projected density}$ Vlasov-Poisson in 1-D in some units:

$$\frac{\partial f}{\partial t} + v \frac{\partial f}{\partial v} - \frac{\partial \phi}{\partial x} \frac{\partial f}{\partial v} = 0$$

$$\frac{\partial^2 \phi}{\partial x^2} = 2\rho(x,t)$$

$$\rho(x,t) \equiv \int f(x,v',t) \mathrm{d}v'$$

N-body simulations solve (in 3-D) by representing continuous dark matter fluid by a set of massive particles, discretizing the collisionless fluid.

Collisionless Fluids

- N-body discretization: $f \sim \text{set of}$ Dirac delta functions
 - Reduce impact by softening gravitational forces (SPH) or using adaptive mesh refinement (AMR)



- Can solve Vlasov-Poisson numerically in 1-D without discretization (Colombi & Touma 2008, 2014):
 - Define small patches in Lagrangian space (initial conditions), where by Liouville theorem, f[x(t), v(t), t] = constant
 - Area of each patch conserved because collisionless fluid is incompressible in phase-space → "waterbags"

Gaussian initial conditions: $f(x, v) = 4e^{-(x^2+v^2)/0.08}$



time evolution \rightarrow

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Approaching the cold case

"Cold" initial conditions have very small velocity dispersion



(Colombi & Touma 2014)

Approaching the cold case



Analytic Approximation: Zel'dovich

The Zel'dovich approximation maps initial Lagrangian coordinates, q, to co-moving Eulerian coordinates, x(Zel'dovich 1970; Shandarin & Zel'dovich 1989; Bouchet et al. 1995):

$$x(q,t) = q - D(t)\nabla_{q}\phi(q)$$

where

D(t) = linear growth function $\phi(q) =$ initial displacement potential, proportional to the gravitational potential.

• Poisson's equation is then

 $D(t)\nabla_q^2\phi(q) = \delta_0(q,t)$

Note that the mapping from q to x is only valid up to shell-crossing!

Analytic Approximation: Zel'dovich

• Before shell-crossing, we can write the density in terms of the Jacobian of the Lagrangian to Eulerian transformation:

$$\frac{\rho(x,t)}{\bar{\rho}} = \left|\frac{\partial x_i}{\partial q_j}\right|^{-1} = \frac{1}{J(q,t)} = 1 + \delta(q(x))$$

(*J* is the determinant of the deformation tensor.)

• The Jacobian can be written in terms of eigenvalues of symmetric matrix $d_{ij}(q)$:

$$d_{ij}(q) = \frac{\partial^2 \phi(q)}{\partial q_i \partial q_j}$$
$$J(q,t) = (1 - D\lambda_1)(1 - D\lambda_2)(1 - D\lambda_3) = \frac{1}{1 + \delta_q}$$

Shell-crossing & Caustics

- A "pancake" forms perpendicular to the principal axis of the deformation tensor with largest negative eigenvalue (if any)
- Pancakes (or walls) are the first structures of the cosmic web
- Can also refer to them as "shell-crossing" or "caustics" but not as delicious



"Pancake theory"

Shell-crossing & Caustics

- In 1-D, Zel'dovich planewave collapse of initially cold distribution (small initial velocity perturbation) forms spirals in phase-space and caustics in projected density
- Outside of caustics is singlestream, within is multistream region where velocity field is multi-valued.
 - (1, 3, 5, ... streams)



Collapse of a one-dimensional halo

substructure visible in phase-space

caustics in projected density





Lagrangian submanifold x = x(q; t)

number of crossings in time t

The Phase-Space Sheet



Time evolution of phase-space fold (Shandarin & Zel'dovich 1989)

- 1-D collapse (left) creates folds in 2-D phase-space
- In the real world (i.e. simulations), cold dark matter undergoes 3-D collapse in 6-D phase space.
- This folding 3-D manifold is called the *dark matter sheet* or *phase-space sheet* when referring to 6dimensional phase-space, or the *Lagrangian submanifold* when referring to the 6 dimensions of (q, x) space.

2-D Lagrangian N-body slice



The ORIGAMI Cosmic Web



Find the phase-space folds by looking for simulation particles that are out of order along orthogonal axes

(Falck, Neyrinck, & Szalay 2012)

$$J(q,t) = (1 - D\lambda_1)(1 - D\lambda_2)(1 - D\lambda_3) = \frac{1}{1 + \delta}$$

Halos collapse along 3 axes, Filaments 2, Walls 1, and Voids 0



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Halo Filament Wall Void

Halo Filament Wall Void



Halo Filament Wall a.,

Tracing the evolution of the manifold

- Tessellate Lagrangian space, with *N*-body particles as vertices of tetrahedra.
- Shell-crossing occurs when tetrahedra invert.
- Instead of mass at particles, can spread mass over tetrahedra volumes.



(Shandarin, Habib, & Heitmann 2012)



(Abel, Hahn, & Kaehler 2012)





(Abel, et al. 2012)



velocity dispersion

of streams Using the phase-space sheet to compute density of a WDM simulation eliminates small granularity introduced with SPH kernel density

(Hahn, Abel, & Kaehler 2013)





density from phase-space sheet

density from

SPH kernel

Summary

- N-body simulations discretely solve the Vlasov-Poisson equations, but cold dark matter is a continuous collisionless fluid.
- The Zel'dovich approximation is a Lagrangian 1st order solution and gives insight on non-linear dynamics.
 - Spirals form in phase-space, and caustics in the 1-D projected density field at boundaries between single-stream and multi-stream regions
- Dark matter structure formation can be represented by collapse of a 3-D manifold in 6-D phase-space
 - Identify elements of cosmic web, count number of streams at any point, improve on N-body simulations, remove numerical fragmentation in WDM simulations, make cool visualizations, etc...